

08-16-00

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SOFER & HAROUN, L.L.P.
PATENT FILING TRANSMITTAL

ATTORNEY DOCKET NO: 807-005

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Box Patent Application
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Washington, D.C. 20231

JC862 U.S. PTO
09/638607
08/15/00

PATENT FILING TRANSMITTAL

Transmitted herewith for filing is the Patent Application of: **Terumi Takashi and Kazuhiko Satake**

For: **DATA REPRODUCTION APPARATUS**

TYPE OF FILING

This new patent application is for a(n):

- ☒ Utility
- ☐ Design
- ☐ Plant
- ☐ Divisional
- ☐ Continuation
- ☐ Continuation-in-part

Benefit of a prior filed application

- ☐ This application claims the benefit of an earlier filed U.S. Patent Application under 35 USC 120.
- ☒ Please accord Applicant the benefit of the priority date of September 27, 1999 to this case pursuant to 35 USC 119. Applicant's claim for priority is based on application 11-271535 filed in Japan on that date.

Filing under 37 CFR 1.53 (Utility) or 37 CFR 1.153 (Design)

- ☒ This is an application filed pursuant to 37 CFR 1.53 or 37 CFR 1.153, permitting receipt of a filing date upon filing of a specification, at least one claim and necessary drawings.
- ☒ In the event any parts of this application are incomplete, please treat this as a filing under 37 CFR 1.53 or 37 CFR 1.153.

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ENCLOSURES

Minimum requirements under 37 CFR 1.53(b) (Utility) or 37 CFR 1.153 (Design)

- ☒ 49 pages of specification;
- ☒ 7 pages of claims;
- ☒ 1 -page(s) of abstract;
- ☒ 21 sheets of formal drawings;
- ☒ A Declaration, Power of Attorney & Petition or listing of inventors;
- and
- ☒ A postcard for return to us as proof of receipt of the above documents.

plus

- ☐ An Assignment of the invention to ____ and Assignment cover sheet;
- ☐ Verified Statement Claiming Small Entity Status (37 CFR 1.9(f) and 1.27(b))
- ☒ Form PTO-1449 (IDS) and copies of the references listed thereon;
- ☐ A certified copy of ____ (country) patent application number 8-236494 (priority document).
- ☐ A preliminary amendment;
- ☐ Declaration of Biological Deposit;
- ☐ Submission of sequence listing, computer readable copy and/or amendment relating thereto for biotechnology invention containing nucleotide and/or amino acid sequence;
- ☐ An associate power of attorney;
- ☐ Other.

DECLARATION OR OATH

The enclosed Declaration or Oath has been executed by:

- ☐ Inventor(s);
- ☐ Legal representative of the inventors (37 CFR 1.42 or 1.43);
- ☐ Joint inventor or person showing proprietary interest on behalf of an inventor who refused to sign or who cannot be reached and this is a petition required by 37 CFR 1.47 and the statement required by 37 CFR 1.47 is attached;
- ☒ Has not been executed and is enclosed for the purposes of identifying the inventors.

INVENTORSHIP STATEMENT

The inventorship for all the claims in this application is:

- ☒ the same;
- ☐ not the same and, as an explanation, a statement is/will be submitted.

LANGUAGE

The application submitted herewith is:

- ☒ in English;
- ☐ in not in English and in terms of 37 CFR 1.52(d) a verified translation is
 - ☐ attached
 - ☐ not attached.

FEE CALCULATION

The filing fee has been calculated as shown below:

	SMALL ENTITY	OR	OTHER THAN A SMALL ENTITY
BASIC FEE Design Patent	\$155		\$310
BASIC FEE Utility Patent	\$345		\$690
EXTRA FEES	RATE	FEE	RATE FEE
TOTAL CLAIMS 12 MINUS 20 = 0	x 9 =	\$ 0	x 18 = \$
INDEP. CLAIMS 5 MINUS 3 = 2	x 39 =	\$	2 x 78 = \$ 156
<input type="checkbox"/> MULTIPLE DEP. CLAIM	+ 130 =	\$	+ 260 = \$
<input type="checkbox"/> ASSIGNMENT	+ 40 =	\$	+ 40 = \$
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TOTAL	\$ 0		\$846.00

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- ☐ Assignment Recordal fees.
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Respectfully submitted,

Dated: 8/15/00

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PATENT

Docket No. 807-005

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicant(s) : Takashi et al.
Serial No. : Not yet assigned
Filed : August 15, 2000
For : DATA REPRODUCTION APPARATUS

EXPRESS MAIL CERTIFICATE

Express Mail Label No. EL701222365US

Date of Deposit August 15, 2000

I hereby certify that the following attached paper(s) or fee

- 1) Patent Application (specif.-49pgs, claims-7 pgs.)
- 2) Formal Drawings (Fig. 1-21)
- 3) Patent Transmittal
- 4) Return Postcard
- 5) Express Mail Certificate
- 6) Declaration-unexecuted
- 7) Information Disclosure Statement, Form PTO-1449
- 8) One Reference

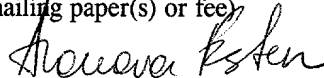
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DATA REPRODUCTION APPARATUS

CROSS-REFERENCE TO RELATED APPLICATION

The present invention is related to U.S.
patent application No. 09/445,217 entitled "Method and
Device for Recording and Reproducing Data" filed April
5 13, 1998, which corresponds to Japanese Patent Laid-
Open Publication (JP-A) No. 11-3565.

This application claims priority from
Japanese Patent Application No. 11-271535 filed
September 27, 1999, the entire content of which is
10 incorporated herein by reference for all purposes.

BACKGROUND OF THE INVENTION

The present invention relates to a data
recording and reproducing apparatus, and more particu-
larly to a data recording and reproducing apparatus for
15 improving the data recording efficiency of a recording
medium.

A general magnetic disk apparatus is now
described as an example of a conventional data record-
ing and reproducing apparatus.

20 The magnetic disk apparatus includes a
magnetic disk, a recording circuit for recording data
in the magnetic disk, a reproduction circuit for
reproducing data from the magnetic disk, and a control
circuit for controlling the recording and reproduction

operation.

Fig. 13 shows a structure of a magnetic disk.

Concentric tracks t are formed on the magnetic disk 2. Sectors c partitioned by gaps g for
5 absorbing rotational variation or fluctuation of the magnetic disk are formed on the track t . Further, servo areas s are formed intermittently in the circumferential direction of the magnetic disk. When one sector c is divided by the servo area s , the sector
10 c is named a split sector. The sector c which is not divided by the servo area s is named a non-split sector.

Fig. 14 is a diagram for explaining an arrangement of information on the track and an index
15 pulse signal IDX , a servo gate signal SG and a sector pulse signal SP for controlling the recording timing and the reproduction timing.

The index pulse signal IDX is a signal indicative of a start point of the track and is
20 generated once per rotation of the magnetic disk 2.

The servo gate signal SG is a signal indicative of the servo area and is generated at regular intervals from the index pulse signal IDX .

The sector pulse signal SP is a signal
25 indicative of a start point of the sector and is generated on the basis of the index pulse signal IDX .

Upon recording of Data

Recording of data is made as follows:

The control circuit activates a write gate signal WG for a sector in which data is to be recorded in response to the sector pulse signal SP. At the same time, the control circuit produces to a data bus NRZ a series of sector information, that is, a bit synchronization information PLO, a symbol synchronization information SYNC, data DATA, an error check code ECC used to perform error detection and correction, and pad information PAD for absorbing reproduction delay. When the series of sector information is produced, the control circuit activates a write gate signal WG.

The recording circuit records the series of sector information produced to the data bus NRZ on the track t of the magnetic disk 2 after the elapse of a delay named a record delay. The time corresponding to the record delay is previously contained in the series of sector information and a length of data actually recorded on the track t is shorter than a length of the series of sector information.

Upon reproduction of Data

Reproduction of data is made as follows:

The control circuit activates a read gate signal RG for a sector from which data is to be reproduced in response to the sector pulse signal SP.

When the read gate signal RG is activated,

the reproduction circuit produces the bit synchronization information PLO to reproduce the symbol synchronization information SYNC, the data DATA, the error check code ECC and the pad information PAD

5 succeeding to the bit synchronization information PLO on the magnetic disk and produces them to the data bus NRZ.

In this connection, the symbol synchronization information SYNC, the data DATA, the error check code ECC and the pad information PAD produced to the data bus NRZ are delayed by a time required for reproduction processing as compared with the the symbol synchronization information SYNC, the data DATA, the error check code ECC and the pad information PAD on the

10 magnetic disk. This delay time is named a reproduction delay time.

The control circuit detects the beginning of the data DATA in response to detection of the symbol synchronization information SYNC on the data bus NRZ

20 and processes the data DATA and the error check code ECC. Further, the control circuit inactivates the read gate signal RG after the time corresponding to the number of bytes of data to be transferred, starting from the detection of the symbol synchronization

25 information SYNC.

When the read gate signal RG is inactivated, the reproduction circuit stops outputting of the data reproduced from the magnetic disk.

SUMMARY OF THE INVENTION

In the conventional magnetic disk apparatus, in order to ensure that the reproduction circuit reads out information in a sector from the magnetic disk
5 until the control circuit inactivates the read gate signal RG after the control circuit has activated the read gate signal RG at the beginning of the sector, it is necessary to provide a pad area PAD longer than the reproduction delay time on the magnetic disk.

10 The reproduction circuit generally adopts the PRML (Partial Response Maximum Likelihood) signal processing system which can reproduce a low-S/N signal, while since the PRML signal processing system has a tendency that the reproduction delay time is increased,
15 there is a tendency that the pad area PAD is also increased.

However, when the pad area PAD increases, there is a problem that the data storage area which can be used effectively is reduced and the data recording
20 efficiency is reduced.

Further, even in the recording operation, it is necessary to provide the pad area PAD for the recording delay time for a recording beginning position of a sector until the write gate signal WG is inacti-
25 vated after it has been activated.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram schematically

illustrating a magnetic disk apparatus according to a first embodiment;

Fig. 2 is a block diagram schematically illustrating a format control circuit and a data flow control circuit in the first embodiment;

Figs. 3A to 3C are timing diagrams showing the relation of information on a track and format control signals in the first embodiment;

Figs. 4A and 4B are timing diagrams showing single sector reproduction operation in the first embodiment;

Figs. 5A and 5B are timing diagrams showing successive sector reproduction operation in the first embodiment;

Figs. 6A and 6B are timing diagrams showing reproduction operation in case where symbol synchronization information SYNC is not detected in the first embodiment;

Figs. 7A and 7B are diagram for explaining control procedures of a sequencer and the data flow control circuit in the first embodiment;

Fig. 8 is a block diagram schematically illustrating a main portion of a magnetic disk apparatus according to a second embodiment;

Figs. 9A and 9B are time diagrams showing successive sector reproduction operation in the second embodiment;

Figs. 10A and 10B are timing diagrams showing

reproduction operation in case where symbol synchroni-
zation information SYNC is not detected in the second
embodiment;

Fig. 11 is a block diagram schematically
5 illustrating a format control circuit and a data flow
control circuit in the second embodiment;

Figs. 12A and 12B are diagrams for explaining
control procedures of a sequencer and the data flow
control circuit in the second embodiment;

10 Fig. 13 is a schematic diagram illustrating a
general track format of a magnetic disk;

Figs. 14A to 14K are timing diagrams showing
the relation of information on a track and format
control signals in a conventional magnetic disk
15 apparatus;

Fig. 15 is a block diagram schematically
illustrating a magnetic recording and reproducing
apparatus according to a third embodiment;

Fig. 16 is a block diagram schematically
20 illustrating a format control circuit and a data flow
control circuit in the third embodiment;

Figs. 17A and 17B are timing diagrams showing
single sector recording operation in the third embodi-
ment;

25 Figs. 18A and 18B are timing diagram showing
single sector reproduction operation in the third
embodiment;

Fig. 19 is a block diagram schematically

illustrating a magnetic recording and reproducing apparatus according to another embodiment;

Fig. 20 is a block diagram schematically illustrating a format control circuit and a data flow control circuit in the embodiment shown in Fig. 19; and

Figs. 21A and 21B are timing diagrams showing single sector recording operation in the embodiment shown in Fig. 19.

DESCRIPTION OF THE EMBODIMENTS

Embodiments of the present invention are now described with reference to the accompanying drawings. The present invention is not limited to the embodiments.

FIRST EMBODIMENT

Fig. 1 schematically illustrates a magnetic disk apparatus according to a first embodiment of the present invention.

The magnetic disk apparatus 1 includes a magnetic disk 2, a recording and reproducing head 3 for converting magnetic information recorded on the magnetic disk 2 into an electric signal, a servo control circuit 4 for controlling to position the recording and reproducing head 3, an R/W (read/write) amplifier 5 for interfacing a record and reproduction signal, a record and reproduction processing circuit 6 for processing digital data, and a data control circuit

7 for controlling recording and reproducing of data.

The record and reproduction processing circuit 6 includes a coding circuit 10 and a data recording circuit 11 constituting a data recording path, a waveform processing circuit 12, a data decision circuit 14, a data correction circuit 15 and the decoding circuit 16 constituting a data reproduction path, a servo demodulation circuit 13 constituting a servo control path, and a SYNC detection circuit 17 constituting synchronization information detecting means for supplying a synchronization information detection signal SBD to the data control circuit 7.

The R/W amplifier 5, the waveform processing circuit 12, the data decision circuit 14, the data correction circuit 15 and the decoding circuit 16 are sometimes named a data reproduction circuit collectively.

The data control circuit 7 includes a microcomputer 20, a format control circuit 21 for producing various control signals on the basis of a servo pulse signal SS and a synchronization information detection signal SBD, a data flow control circuit 22 constituting data processing means for controlling data on the data bus NRZ under control of the format control circuit 21, a buffer control circuit 23, a buffer 24, an ECC correction circuit 25, and an interface control circuit 26 constituting a connection portion with an external processing apparatus. The data flow control

circuit 22, the buffer control circuit 23 and the ECC correction circuit 25 are sometimes named a data processing circuit collectively.

The internal circuits included in the record and reproduction processing circuit 6 and the data control circuit 7 are connected through signal lines such as buses or paths and signals are transmitted among the internal circuits in the arrow direction shown in Fig. 1. Further, the record and reproduction processing circuit 6 and the data control circuit 7 are also connected through signal lines.

Operation Except Recording and Reproduction Operation

The servo control circuit 4 performs control using servo information of the servo area in the operation except the recording and reproducing operation, that is, in the unrecording and unreproducing operation and the recording and reproducing head 3 is positioned on any track.

The timing of the servo information is indicated by the servo gate signal SG of the format control signals produced by the format control circuit 21.

When the servo gate signal SG is activated, the servo demodulation circuit 13 uses the servo information obtained through the recording and reproducing head 3, the R/W amplifier 5 and the waveform processing circuit 12 to produce the servo pulse signal

SS indicating the servo area, which signal is supplied to the format control circuit 21. Further, the servo demodulation circuit 13 supplies a track position shift or deviation amount of the recording and reproducing head 3 to the servo control circuit 4.

The servo control circuit 4 feeds back the position shift amount so that the recording and reproducing head 3 tracks or follows the track.

Recording Operation

10 The recording operation is started when the external processing apparatus sends out a write command.

Subsequently to the write command, the external processing apparatus supplies data to be
15 recorded to the interface control circuit 26.

The interface control circuit 26 receives the write command from the external processing apparatus and supplies the write command and a logical address contained therein to the microcomputer 20.

20 The microcomputer 20 converts the logical address into a physical address and supplies a seeking instruction for the recording and reproducing head 3 to the servo control circuit 4.

The servo control circuit 4 moves the record-
25 ing and reproducing head 3 to a track corresponding to the physical address. In parallel to this movement, the data to be recorded is temporarily stored in the

buffer 24 through the interface control circuit 26 and the buffer control circuit 23.

The format control circuit 21 prepares the servo gate signal SG, the index pulse signal IDX and
5 the sector pulse signal SP on the basis of the servo pulse signal SS.

The format control circuit 21 activates the write gate signal WG when the sector number corresponding to the sector pulse signal SP is coincident
10 with a record sector number given by the physical address. The format control circuit 21 controls the data flow control circuit 22 to output a series of sector information, that is, the bit synchronization information PLO, the symbol synchronization information
15 SYNC, the data DATA temporarily stored in the buffer 24, the error check code ECC constituting the correction information for performing data correction prepared by the ECC correction circuit 25, and the pad information PAD constituting the additional area, to
20 the data bus NRZ successively.

Further, POST information composed of several bytes for ensuring data processing of the error check code ECC is provided between the error check code ECC and the pad information PAD, while the POST information
25 is not directly related to the present invention and accordingly description thereof is omitted.

The outputted sector information is coded to a specific code by the coding circuit 10 and is

supplied to the data recording circuit 11.

The data recording circuit 11 adds a data correction code to the coded parallel data row to be outputted to the R/W amplifier 5 as a serial data string.

The R/W amplifier 5 records the serial data string on the pertinent track as sector information by means of the recording and reproducing head 3.

Reproduction Operation

The reproduction operation is started when the external processing apparatus sends out a read command. The timing of the control signal is described later.

The interface control circuit 26 receives the read command and supplies a logical address contained in the read command to the microcomputer 20.

The microcomputer 20 converts the logical address into a physical address and supplies a seeking instruction to the servo control circuit 4 so that the recording and reproducing head 3 is moved on a track from which data is to be reproduced.

The format control circuit 21 prepares the sector pulse signal SP on the basis of the servo pulse signal SS processed by the recording and reproducing head 3, the R/W amplifier 5, the waveform processing circuit 12 and the servo demodulation circuit 13. The sector pulse signal SP leads the sector pulse signal SP

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in the recording operation.

When the sector number corresponding to the sector pulse signal SP is coincident with the sector number for reproduction given by the physical address, 5 the format control circuit 21 activates the read gate signal RG.

The sector information is reproduced as serial digital data by means of the R/W amplifier 5, the waveform processing circuit 12 and the data 10 decision circuit 14.

The SYNC detection circuit 17 detects the symbol synchronization information SYNC from the sector information and activates the synchronization information detection signal SBD

15 The data correction circuit 15 performs correction of data by means of the data correction code (CRC, ECC or the like) after the synchronization information detection signal SBD has been activated.

The decoding circuit 16 outputs the serial 20 data string to the data bus NRZ as parallel data.

The format control circuit 21 counts the number of bytes of data to be transferred on the basis of the synchronization information detection signal SBD and inactivates the read gate signal RG when the sector 25 end position is reached. That is, the format control circuit 21 calculates the sector end position on the basis of the synchronization information detection signal SBD and notifies the calculated end position to

the record and reproduction processing circuit 6 side.
By changing the timing for inactivating the read gate
signal RG on the basis of the calculated end position,
the timing for inactivating the read gate signal RG
5 does not contain the reproduction delay time. Accord-
ingly, the pad area PAD is minimized irrespective of
the reproduction delay time.

The arrival of data to the data flow control
circuit 22 is delayed by the processing time in the
10 data correction circuit 15 and the decoding circuit 16,
that is, the reproduction delay time as compared with
the synchronization information detection signal SBD.
The data flow control circuit 22 counts the number of
bytes corresponding to the reproduction delay time
15 after the synchronization information detection signal
SBD is activated and then stores data in the buffer 24
by means of the buffer control circuit 23.

The ECC correction circuit 25 performs the
error verification of the data stored in the buffer 24
20 on the basis of the error check code ECC and when any
error is detected, the ECC correction circuit 25
corrects the error.

The data stored in the buffer 24 is sent out
to the external processing apparatus through the buffer
25 control circuit 23 and the interface control circuit 26
under control of the microcomputer 20 when the data
correction is completed or when there is no error in
the data.

Fig. 2 schematically illustrates the internal configuration of the format control circuit 21 and the data flow control circuit 22.

The format control circuit 21 includes a
5 servo control signal production circuit 30, an index pulse production circuit 31, a sector pulse production circuit 32 and a sequencer 33.

The servo control signal production circuit 30 produces the servo gate signal SG on the basis of
10 the servo pulse signal SS.

The index pulse production circuit 31 discriminates the servo pulse signal SS in the period that the servo gate signal SG is active and produces the index pulse signal IDX.

15 The sector pulse production circuit 32 produces the sector pulse signal SP having phases different depending on the reproduction operation and the recording operation on the basis of the index pulse signal IDX.

20 The sequencer 33 is to control the sector format and produces the write gate signal WG indicative of the sector recording period, the read gate signal RG indicative of the sector reproduction period and a selection signal SEL and a load signal LD for control-
25 ling the data flow control circuit 22.

The data flow control circuit 22 includes a fixed data production circuit 34, an FIFO 38, a selection circuit 35, a reproduction delay counter 36

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and the data transfer counter 37.

The fixed data production circuit 34 produces a code string of the bit synchronization information PLO, the symbol synchronization information SYNC and
5 the pad information PAD and is connected to a first terminal of the selection circuit 35.

The FIFO 38 produces a code string of the data DATA and the error check code ECC supplied from the buffer control circuit 23 and is connected to a
10 second terminal of the selection circuit 35.

The selection circuit 35 selects the fixed data production circuit 34 when the selection signal SEL from the sequencer 33 is "1" and selects the FIFO 38 when the selection signal SEL is "0" to produce the
15 signal from the selected circuit to the data bus NRZ.

Figs. 3A to 3C show the timing of the servo gate signal SG, the index pulse signal IDX and the sector pulse signal SP and the data arrangement on the magnetic disk 2. Figs. 3A to 3C show an example that 3
20 servo areas and 8 sectors are provided during one rotation of the magnetic disk 2.

The servo gate signal SG is active in each of the servo areas. The index pulse signal IDX becomes active once each time the magnetic disk 2 makes one
25 rotation and accordingly in the embodiment the index pulse signal IDX becomes active once during the three-servo period.

The sector pulse signal SP is active at the

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beginning position of each sector. Small gap areas are formed between the sectors. One sector includes the bit synchronization information PLO, the symbol synchronization information SYNC, the data DATA, the error check code ECC and the pad area PAD.

Recording Operation

In the recording operation, as shown in Fig. 3B, the sector pulse signal SP is active at the sector beginning position. Further, the write gate signal WG is active in synchronism with the sector pulse signal SP in order to record data in the sector.

A series of sector information including the bit synchronization information PLO, the symbol synchronization information SYNC, the data DATA, the error check code ECC and the pad information PAD to be recorded is prepared by the fixed data production circuit 34, the FIFO 38 and the selection circuit 35 on the basis of the selection signal SEL produced by the sequencer 33. That is, the sequencer 33 first sets the selection signal SEL to "1" to thereby select the output of the fixed data production circuit 34 so that the bit synchronization information PLO and the symbol synchronization information SYNC are outputted to the data bus NRZ. Then, the sequencer 33 sets the selection signal SEL to "0" to thereby select the output of the FIFO 38 so that the data DATA and the error check code ECC are outputted to the data bus NRZ.

The sequencer 33 then sets the selection signal SEL to "1" to thereby select the output of the fixed data production circuit 34 so that the pad information PAD is outputted to the data bus NRZ. Finally, the
5 sequencer 33 inactivates the write gate signal WG and ends the recording operation.

Reproduction Operation

In the reproduction operation, as shown in Fig. 3C, the sector pulse signal SP leads the data
10 recording operation. This reason is that the read gate signal RG is certainly controlled to be active at the leading position of the sector against variation of the sector beginning position due to the rotational variation. That is, when the read/write signal is in
15 the state indicating the reproduction operation, the sector pulse production circuit 32 advances the phase of the sector pulse signal SP as compared with the case where the read/write signal is in the state indicating the recording operation.

20 The sequencer 33 activates the read gate signal RG at the sector beginning position with reference to the sector pulse signal SP. Then, the sequencer 33 inactivates the read gate signal RG after the elapse of a prescribed number of bytes counted from
25 detection of the symbol synchronization information SYNC.

When the sequencer 33 detects the

synchronization information detection signal SBD supplied from the SYNC detection circuit 17, the sequencer starts counting operation of the reproduction delay counter 36 by means of the load signal LD. When
5 the reproduction delay counter 36 counts the number of bytes corresponding to the reproduction delay time of the data correction circuit 15 and the decoding circuit 16, the reproduction delay counter produces an ST signal. The data transfer counter 37 is triggered by
10 the ST signal and then counts data of a prescribed number of bytes. During the counting of the data, the data DATA and the error check code ECC on the data bus NRZ are supplied to the buffer control circuit 23 through the FIFO 38.

15 The prescribed number of bytes is the number of bytes corresponding to the data DATA and the error check code ECC basically, while it is different depending on the case of the non-split sector that is not divided by the servo area and the case of the split
20 sector that is divided by the servo area.

Figs. 4A and 4B show the output timing of the control signals in the reproduction operation of a single data sector.

Fig. 4A shows the output timing of the
25 control signals for the non-split sector (sector #2).

The read gate signal RG is active from the sector beginning position on the magnetic disk to the middle position of the pad area PAD.

The synchronization information detection signal SBD is active when the symbol synchronization information SYNC is detected by the SYNC detection circuit 17 and is inactive when the read gate signal RG becomes inactive.

The data bus NRZ of the decoding circuit 16 is in the high impedance state (Hi-Z) at the beginning of the reproduction operation and the data DATA, the error check code ECC and data in the pad area PAD are outputted after the elapse of the reproduction delay time starting from outputting of the synchronization detection signal SBD.

The synchronization information detection signal SBD and the data on the data bus NRZ having the above-mentioned timing relation are controlled by the format control circuit 21 and the data flow control circuit 22 as described above.

Fig. 4B shows the output timing of the control signals for the split sector (sector #3).

The read gate signal RG for the first half sector (named sector #3(a)) positioned before the servo area is active from the beginning position of the bit synchronization information PLO of the sector #3(a) to the middle portion of the pad area PAD. The read gate signal RG for the second half sector (named sector #3(b)) positioned behind the servo area is active from the beginning position of the bit synchronization information PLO of the sector #3(b) to the middle

portion of the pad area PAD.

The synchronization information detection signal SBD becomes active when the symbol synchronization information SYNC of the sector #3(a) is detected
5 by the SYNC detection circuit 17 and becomes inactive when the read gate signal RG becomes inactive.

Further, the synchronization information detection signal SBD becomes active when the symbol synchronization information SYNC of the sector #3(b) is detected
10 by the SYNC detection circuit 17 and becomes inactive when the read gate signal RG becomes inactive.

The data DATA(1) and the pad information PAD are produced through the data bus NRZ after the elapse of the reproduction delay time from the synchronization
15 information detection signal SBD detected in the sector #3(a) and thereafter the data bus NRZ becomes the high-impedance state. Further, the data DATA(2), the error check code ECC and the pad information PAD are produced through the data bus NRZ after the elapse of the
20 reproduction delay time from the synchronization information detection signal SBD detected in the sector #3(b) and thereafter the data bus NRZ becomes the high-impedance state. The reproduction delay time for the sector #3(a) is equal to that for the sector #3(b) and
25 further the servo period is not zero. Accordingly, the sector #3(a) does not collide with the sector #3(b) on the data bus NRZ.

The synchronization information detection

signal SBD and the data on the data bus NRZ having the above-mentioned timing relation are controlled by the format control circuit 21 and the data flow control circuit 22 as described above.

5 Figs. 5A and 5B show the output timing of the control signals in the reproduction operation for successive data sectors.

Fig. 5A shows the output timing of the control signals for successive reproduction of non-
10 split sectors (sectors #4 and #5).

The read gate signal RG, the synchronization information detection signal SBD and the data bus NRZ are produced at the same timing as in the reproduction operation for the single sector.

15 The synchronization information detection signal SBD becomes inactive at the same time that the read gate signal RG for the sector #4 becomes inactive. Accordingly, the format control circuit 21 can detect the beginning position of the symbol synchronization
20 information SYNC in the next sector #5 in accordance with the synchronization information detection signal SBD.

The sectors #4 and #5 do not overlap each other on the data bus NRZ since the gap area GAP, the
25 bit synchronization information PLO for the sector #5 and symbol synchronization information SYNC are not reduced to zero.

Accordingly, the data for each sector can be

stored in the pertinent buffer 24 by the format control circuit 21 and the data flow control circuit 22.

Fig. 5B shows the output timing of the control signals for successive reproduction of the split sector (sector #3) and the non-split sector (sector #4).

The read gate signal RG, the synchronization information detection signal SBD and the data bus NRZ are produced at the combined timing of the timing in the reproduction operation of the single split sector and the timing in the reproduction operation of the single non-split sector

The synchronization information detection signal SBD is the same as Fig. 5A. Accordingly, the format control circuit 21 can detect the beginning position of the pertinent symbol synchronization information SYNC in accordance with the synchronization information detection signal SBD.

Further, similarly, the sectors do not overlap each other on the data bus NRZ. Accordingly, the data for each sector can be stored in the pertinent buffer 24.

Referring now to Figs. 6A and 6B, operation in case where the symbol synchronization information SYNC cannot be detected exactly due to decision error of the data decision circuit 14 is described.

Fig. 6A shows the timing in case where the symbol synchronization information SYNC for the sector

#5 cannot be detected exactly in the successive reproduction operation of the non-split sectors (sectors #4 and #5).

The reproduction operation for the sector #4
5 is the same as Fig. 5A.

The read gate signal RG for the sector #5 is active at the beginning position of the bit synchronization information PLO, while since the synchronization information detection signal SBD is not active during a
10 predetermined period, the sequencer 33 inactivates the read gate signal RG. The predetermined period is assumed to be a period slightly longer than the period from the sector beginning position to the symbol
15 synchronization information SYNC. Since the synchronization information detection signal SBD is not active, the data correction circuit 15 and the decoding circuit 16 do not produce the data DATA (DATA #5) for the sector #5 to the data bus NRZ. Accordingly, the data
20 DATA (DATA #4) for the sector #4 is normally stored in the buffer 24, while the data DATA (DATA #5) for the sector #5 is not stored in the buffer 24. Therefore, the reproduction operation for the sector #5 is made again by retrying processing.

Fig. 6B shows the timing in case where the
25 symbol synchronization information SYNC for the sector (sector #3(2)) positioned behind the servo area for the split sector #3 cannot be detected exactly in the successive reproduction operation for the split sector

(sector #3) and the non-split sector (sector #4).

The reproduction operation for the sector (sector #3(1)) positioned before the servo area for the split sector #3 is the same as Fig. 5B.

5 The read gate signal RG for the sector (sector #3(2)) positioned behind the servo area for the split sector #3 is active at the beginning position of the bit synchronization information PLO, while since the synchronization information detection signal SBD is
10 not active during a predetermined period, the sequencer 33 inactivates the read gate signal RG. Since the synchronization information detection signal SBD is not active, the data correction circuit 15 and the decoding circuit 16 do not output the data DATA (DATA #3(2)) of
15 the sector #3(2) to the data bus NRZ.

The reproduction operation for the non-split sector #4 is the same as Fig. 5B. Accordingly, the reproduction operation for the data of the split sector #3 is made again by retrying processing.

20 Figs. 7A and 7B show control procedures of the sequencer 33 and the data flow control circuit 22.

The control procedures include usual processing (1) for processing the non-split sector and the split sector and exceptional processing (2) performed
25 when the symbol synchronization information SYNC is not detected within a prescribed time.

The usual processing shown in Fig. 7A is made in steps 1 to 9.

The sequencer 33 activates the read gate signal RG in step 1. In step 2, it is confirmed whether the synchronization information detection signal SBD is detected within a fixed period or not and

5 when it is detected, the control proceeds to step 3. When the synchronization information detection signal SBD is not turned to active within the fixed period, the control proceeds to the exceptional processing. In step 3, the control comes in the waiting state until

10 the prescribed number of bytes is counted in order to ensure to maintain the read gate signal RG to be active during the data DATA, the error check code ECC and the pad area PAD. The prescribed number of bytes is the number of bytes equal to a sum of the data DATA, the

15 error check code ECC and the pad area PAD for the non-split sector and the prescribed number of bytes is the number of bytes equal to a sum of the data DATA and the pad area PAD existing until the servo area (in the example of Fig. 4B, the total byte number of DATA (1)

20 and its subsequent pad area PAD) for the split sector. In step 4, the read gate signal RG is inactivated.

In the case of the non-split sector, since the data of the prescribed number of bytes is processed, the operation for the non-split sector is

25 ended in step 4.

In the case of the split sector, the control comes in the waiting state until the servo period passes in step 5 and then the split sector positioned

behind the servo area is processed. The read gate signal RG is activated again in step 6 and the synchronization information detection signal SBD is detected in step 7. When the synchronization information detection signal SBD is not detected within the fixed period, the control proceeds to the exceptional processing. After the control is in the waiting state during the prescribed number of bytes (in the example of Fig. 4B, the total byte number of the DATA (2), the ECC and the pad area PAD) in step 8, the read gate signal RG is inactivated in step 9.

The data flow control circuit 22 continues data transfer basically when data is being transferred except steps 3 and 8. In steps 3 and 8, the control is in the waiting state during the number of reproduction delay bytes in response to the load signal LD supplied from the sequencer 33 and data of the prescribed number of bytes is transferred.

The exceptional processing shown in Fig. 7B is made in steps 1 and 2.

The sequencer 33 inactivates the read gate signal RG in step 1 and notifies occurrence of data error to the microcomputer 20 in step 2 to make retrying processing.

The data flow controller 22 continues data transfer when data is being transferred.

According to the magnetic disk apparatus 1 of the first embodiment, the synchronization information

detection signal is not produced from the data correction circuit 15 and the decoding circuit 16 which produce the outputs delayed by the reproduction delay time but the synchronization information detection

5 signal SBD is produced from the SYNC detection circuit 17 capable of producing the output without substantial delay. Accordingly, the format control circuit 21 can inactivate the read gate signal RG exactly at the end position of the sector on the magnetic disk on the

10 basis of the synchronization information detection signal SBD without influence of the reproduction delay time. Accordingly, it is necessary to provide the pad area PAD longer than the reproduction delay time in the end portion of the sector in order to ensure that the

15 record and reproduction processing circuit 6 reads out information of a sector from the magnetic disk. Thus, the pad area PAD is minimized and the effectively usable data storage area can be increased, so that the data recording efficiency can be improved. Further,

20 since data is produced to the data bus NRZ while delayed by the reproduction delay time, the data flow control circuit 22 is adapted to process the data delayed by the reproduction delay time.

In other words, according to the present

25 invention, the format control and the data control can be made separately. Consequently, the pad area PAD can be reduced to the minimum and the effective data recording area can be increased, so that the data

recording efficiency can be improved.

Concretely, the pad area PAD requiring about 8 bytes in the prior art can be reduced to about 2 bytes. Further, the pad area PAD requiring 512 bytes or more in the prior art when the reproduction delay reaches 1 sector (about 512 bytes) can be also reduced about 2 bytes (the data recording efficiency is reduced to about 40% for the pad area PAD of 512 bytes or more but can ensure about 75% for the pad area PAD of about 2 bytes).

SECOND EMBODIMENT

In the second embodiment, the synchronization information detection signal SBD of the signals for connecting the record and reproduction processing circuit 6 and the data control circuit 7 shown in Fig. 1 is deleted.

Fig. 8 is a schematic diagram illustrating a main portion of a magnetic disk apparatus according to the second embodiment of the present invention. In Fig. 8, a record and reproduction processing circuit 6' and a data control circuit 7' are used in order to distinguish the record and reproduction processing circuit 6 and the data control circuit 7 shown in Fig. 1 therefrom.

The record and reproduction processing circuit 6' includes the coding circuit 10 and the data recording circuit 11 constituting a data recording

path, the waveform processing circuit 12, the data
decision circuit 14, the data correction circuit 15 and
the decoding circuit 16 constituting a data reproduc-
tion path, the servo demodulation circuit 13 constitut-
5 ing a servo control path, and the SYNC detection
circuit 17 and a SYNC code production circuit 40 for
transmitting a SYNC information through the data bus
NRZ to the data control circuit 7'.

The data control circuit 7' includes the
10 interface control circuit 26 (not shown), the
microcomputer 20, the buffer 24, the buffer control
circuit 23, the ECC correction circuit 25, and a format
control circuit 41 and a data flow control circuit 42
for performing format control and data processing on
15 the basis of information from the data bus NRZ.

Figs. 9A and 9B are diagrams for explaining
data flow on the data bus NRZ between the record and
reproduction processing circuit 6' and the data control
circuit 7' in the reproduction operation. For
20 simplification of the drawings, it is assumed that the
sector reproduction operation performed before the read
gate signal RG becomes active has been completed.

Fig. 9A shows successive reproduction
operation for a non-split sector.

25 When the read gate signal RG is active at the
beginning position of the sector #4, the waveform
processing circuit 12 and the data decision circuit 14
starts the data decision operation for the sector.

When the SYNC detection circuit 17 detects the symbol synchronization information SYNC, the SYNC detection circuit activates the synchronization information detection signal SBD. Since there is no transfer of data on the data bus NRZ, when the synchronization information detection signal SBD is active, the SYNC code production circuit 40 produces a particular symbol synchronization information SYNC to the data bus NRZ.

10 When the synchronization information detection signal SBD is active, the data correction circuit 15 and the decoding circuit 16 starts correction and decoding of data and produces data (DATA #4) to the data bus NRZ after the elapse of the reproduction delay time.

The data bus NRZ becomes high impedance (Hi-Z) during the period from the particular symbol synchronization information SYNC to the beginning of the data (DATA #4).

20 The format control circuit 14 activates the load signal LD when the particular symbol synchronization information SYNC is detected.

When the Load signal LD is active, the data flow control circuit 42 transfers the data (DATA #4) on the data bus NRZ after the elapse of the reproduction delay time to the buffer control circuit 23.

The read gate signal RG corresponding to the sector #4 is active at the final position of the sector

#4, while since the data (DATA #4) and data of the subsequent error check code ECC and pad information PAD have been already taken in internal memory circuit of the data correction circuit 15 and the decoding circuit 5 16, the data are produced to the data bus NRZ from the data correction circuit 15 and the decoding circuit 16 subsequently.

When the read gate signal RG corresponding to the sector #5 is active, the data correction circuit 15 10 and the decoding circuit 16 interrupt outputting to the data bus NRZ temporarily. Accordingly, the data bus NRZ becomes high impedance (Hi-Z).

When the SYNC detection circuit 17 detects the symbol synchronization information SYNC for the 15 sector #5, the synchronization information detection signal SBD is active and the SYNC code production circuit 40 produces the particular symbol synchronization information SYNC to the data bus NRZ.

Subsequently, the data correction circuit 15 20 and the decoding circuit 16 resume outputting the data (DATA #4) and the subsequent error check code ECC and pad information PAD stored in the internal memory circuit to the data bus NRZ.

At the same time, the data correction circuit 25 15 and the decoding circuit 16 perform correction and decoding processing of data of the sector #5 by means of the internal memory circuit, while since the reproduction delay time is not reached, outputting

thereof to the data bus NRZ is not made. When outputting of the pad information PAD of the sector #4 is completed, the data bus NRZ becomes high impedance (Hi-Z).

5 Thereafter, when the reproduction delay time elapses, the data (DATA #5) and the subsequent data including the error check code ECC and the pad information PAD are outputted from the data correction circuit 15 and the decoding circuit 16 to the data bus NRZ. Fig. 9A shows the case where the read gate signal RG is not active during outputting of the data (DATA #5) of the sector #5 to the data bus NRZ. When the read gate signal RG is active, the outputting thereof to the data bus NRZ is divided in the same manner as
10 the data (DATA #4) of the sector #4.

Fig. 9B shows successive reproduction operation of the split sector and the non-split sector.

In the same manner as the Fig. 9A, when the read gate signal RG is active at the beginning position
20 of the sector #3 and the symbol synchronization information SYNC is detected, the particular symbol synchronization information SYNC is outputted to the data bus NRZ. After the elapse of the reproduction delay time, the data (DATA #3(1)) positioned before the
25 servo area is outputted to the data bus NRZ.

After the passage of the servo area, when the read gate signal RG is active again at the beginning position of the data (DATA #3(2)) positioned behind the

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servo area, outputting of the data (DATA #3(1)) positioned before the servo area is interrupted temporarily and the data bus NRZ becomes high impedance (Hi-Z).

5 When the symbol synchronization information SYNC of the data (DATA #3(2)) positioned behind the servo area is detected, the particular symbol synchronization information SYNC is outputted to the data bus NRZ.

10 Subsequently, outputting of the data (DATA #3(1)) positioned before the servo area is resumed.

 Thereafter, when the reproduction delay time elapses, the data (DATA #3(2)) positioned behind the servo area is outputted to the data bus NRZ from the
15 data correction circuit 15 and the decoding circuit 16, while in this example since the read gate signal RG corresponding to the sector #4 is first active, the outputting is interrupted temporarily and the data bus NRZ becomes high impedance (Hi-Z).

20 When the symbol synchronization information SYNC for the sector #4 is detected, the particular symbol synchronization information SYNC is outputted to the data bus NRZ.

 Subsequently, outputting of the data (DATA
25 #3(2)) positioned behind the servo area is resumed.

 Thereafter, when the reproduction delay time elapses, the data (DATA #4) is outputted to the data bus NRZ from the data correction circuit 15 and the

decoding circuit 16.

The control method in case where the symbol synchronization information SYNC is not detected is now described.

5 Fig. 10A shows the timing in case where the symbol synchronization information SYNC for the sector #5 is not detected in the successive reproduction operation of the non-split sector.

10 The particular symbol synchronization information SYNC for the sector #4 is outputted to the data bus NRZ and after the elapse of the reproduction delay time, a part of the data (DATA #4) is outputted. When the read gate signal RG for the sector #5 is active, outputting of the data (DATA #4) is interrupted
15 temporarily. Thereafter, since the symbol synchronization information SYNC for the sector #5 is not detected, the particular symbol synchronization information SYNC for the sector #5 is not also outputted. Accordingly, outputting of the data (DATA #4) is not
20 also resumed. However, since the synchronization information detection signal SBD is not active within the predetermined period, the read gate signal RG for the sector #5 is inactive, so that outputting of the data (DATA #4) is resumed. Thus, outputting of the
25 data for the sector #4 is completed.

Fig. 10B shows the timing in case where the symbol synchronization information SYNC positioned behind the servo area for the split sector #3 is not

detected in the successive reproduction operation of the split sector and the non-split sector.

When the data (DATA #3(1)) positioned before the servo area for the split sector #3 is being
5 outputted to the data bus NRZ, the read gate signal RG for the data DATA #3(2) positioned behind the servo area for the split sector #3 is active and accordingly outputting is interrupted temporarily. The symbol synchronization information SYNC for the data DATA
10 #3(2) positioned behind the servo area for the split sector #3 is not detected and accordingly when the read gate signal RG is inactive, outputting of the data (DATA #3(1)) positioned before the servo area for the split sector #3 is resumed. However, since the symbol
15 synchronization information SYNC is not detected, correction and decoding processing of the data DATA #3(2) positioned behind the servo area for the split sector #3 is not performed and the data is not outputted to the data bus NRZ. In this case, since the
20 data for the sector #3 disappears partially, data recovery processing such as retrying is made.

Fig. 11 is a schematic diagram illustrating the format control circuit 41 and the data flow control circuit 42.

25 As compared with Fig. 2, the circuits shown in Fig. 11 is different from Fig. 2 in that the sequencer 50 is provided instead of the sequencer 33 of Fig. 2, data on the data bus NRZ is inputted to the

sequencer 50 instead of inputting the synchronization information detection signal SBD to the sequencer 33, and a hold signal HD is supplied from the sequencer 50 to a data transfer counter 51.

5 The recording operation of the sequencer 50
is the quite same as that of the sequencer 33 of Fig.
2.

The sequencer 50 in the reproduction operation activates the read gate signal RG and the hold signal HD for temporarily holding the counting operation of the data transfer counter 51. Further, when the sequencer 50 detects the particular symbol synchronization information SYNC on the data bus NRZ, the sequencer activates the load signal LD and inactivates the hold signal HD.

The reproduction delay counter 36 activates the ST signal after delaying it by the number of bytes for the reproduction delay in comparison with the load signal LD.

20 The data transfer counter 51 counts the
number of data transferred to the buffer control
circuit 23, while when the hold signal HD is active,
the data transfer is temporarily interrupted when the
read gate signal RG is turned to active. When the hold
25 signal HD is turned to inactive, the data transfer is
resumed.

Figs. 12A and 12B show control procedures of the sequencer 50 and the data flow control circuit 42.

The control procedures include usual processing (1) for processing the non-split sector and the split sector and exceptional processing (2) performed when the symbol synchronization information SYNC is not
5 detected within a prescribed time.

The usual processing shown in Fig. 12A is made in steps 1 to 9.

The sequencer 50 activates the read gate signal RG in step 1 and when the particular symbol
10 synchronization information SYNC is detected on the data bus NRZ within a fixed period in step 2, the control proceeds to step 3 and when it is not detected, the control proceeds to the exceptional processing. In step 3, the control is in the waiting state until the
15 prescribed number of bytes is counted. In step 4, the read gate signal RG is inactivated. In the case of the non-split sector, since the data processing of the prescribed number of bytes is completed, the processing is ended in step 4. In the case of the split sector,
20 the control is in the waiting state until the servo area passes in step 5 and the read gate signal RG is activated again in step 6. In step 7, when the particular symbol synchronization information SYNC is detected within the fixed period, the control proceeds
25 to step 8 and when it is not detected, the control proceeds to the exceptional processing. In step 8, the control is in the waiting state during the prescribed number of bytes. In step 9, the read gate signal RG is

inactivated.

In step 1 in which the read gate signal RG is active, the data flow control circuit 42 temporarily stops data transfer when data is being transferred. In
5 step 2, the temporary stop of the data transfer is continued and when the particular symbol synchronization information SYNC is detected and the control proceeds to step 3, the data transfer is resumed when the data transfer is temporarily stopped and when the
10 data transfer is not temporarily stopped, the control is in the waiting state during the number of reproduction delay bytes in response to the load signal LD supplied from the sequencer 50 and the data transfer of the prescribed number of bytes is made. In steps 4
15 and 5, the data transfer is continued when the data transfer is being made. Steps 6 to 9 are the same as steps 1 to 5.

The exceptional processing shown in Fig. 12B is made in steps 1 and 2.

20 The sequencer 50 inactivates the read gate signal RG in step 1 and notifies occurrence of data error to the microcomputer 20 in step 2 to make retrying processing.

The data flow control circuit 42 resumes the
25 data transfer when the data transfer is in the temporary stop state in step 1. The data transfer is stopped in step 2.

According to the second embodiment, the

particular symbol synchronization information SYNC on the data bus NRZ is used instead of the synchronization information detection signal SBD, so that the SYNC information can be notified from the record and reproduction processing circuit 6' to the data control circuit 7. Accordingly, when the circuit is fabricated by an LSI, the number of pins and a wiring area for the LSI can be reduced.

THIRD EMBODIMENT

10 In the third embodiment, a control signal indicating the data output period is provided newly to attain simplification of control. Fig. 15 is a schematic diagram illustrating a magnetic recording and reproducing apparatus to which the third embodiment is applied. As compared with Fig. 1, the third embodiment of Fig. 15 is different from Fig. 1 in that the LD signal for causing the format control circuit 21 to control the data flow control circuit 22 is changed to a newly provided VALID signal. The VALID signal is a
15 bidirectional signal indicating that data on the NRZ is ensured and is supplied to the decoding circuit 16, the coding circuit 10 and the data flow control circuit 22. The VALID signal is different depending on the recording operation and the reproduction operation and
20 indicates an output period of NRZ data. Operation of changing the direction of the VALID signal is made by data flow control circuit 22 in the recording operation

and by the decoding circuit 16 in the reproduction operation. The decoding circuit 16 has the function of prescribing the data range.

Recording Operation

5 The data flow control circuit 22 newly includes, as shown in a configuration example of Fig. 16, a write valid production circuit 60 for producing a valid signal in the recording operation in addition to the configuration of Fig. 2. The fixed data production
10 circuit 34 and the selection circuit 35 are assumed to be included in the coding circuit 10. The data string sent out from the buffer control circuit is once stored in the FIFO 38 and then when the VALID signal produced by the write valid production circuit 60 is activate,
15 the output data of the FIFO 38 is outputted to the coding circuit 10 as the NRZ data. The coding circuit 10 has the same function as the fixed data production circuit 34 and records data such as PLO and SYNC together with the converted NRZ data.

20 The above operation timing is shown in Figs. 17A and 17B. The VALID signal has the same timing in both cases where the sector area is not divided by the servo area and where the sector area is divided by the servo area and the VALID signal is active only when
25 data on the data bus NRZ is settled. When the WG signal rises after the elapse of the record delay time, the PLO signal is produced from the data recording

circuit 11 and when the SBD signal rises, the SYNC signal is produced from the data recording circuit 11. When the NRZ data in the period that the VALID signal is active is processed, the SBD signal falls and the POST signal is recorded. Thereafter, the WG signal falls and the series of recording operation is completed.

Reproduction Operation

In the reproduction operation, the decoding circuit 16 activates the VALID signal at the same time that the NRZ data is sent out. The VALID signal and the NRZ data are supplied to the FIFO 38 of the data flow control circuit 22 as shown in Fig. 16. The FIFO 38 takes in the NRZ data when the VALID signal is active and thereafter the FIFO 38 sends out the data to the buffer control circuit.

The VALID signal is produced in accordance with the timing of the data outputted in the NRZ data as shown in Figs. 18A and 18B in detail. At this time, the rising edge of the SBD signal is produced in response to detection of the SYNC area on the recording medium, while since the NRZ data and the VALID signal are produced after the elapse of the reproduction delay time starting from the detection of the SYNC, the SBD signal is asserted at an earlier timing than the NRZ data and the VALID signal. The format control circuit 21 produces a falling edge of the RG signal in the POST

area on the recording medium from the assert position of the SBD signal. The SBD signal is negated in accordance with the falling edge of the RG signal. The record and reproduction processing circuit 6 detects
5 the period from the assert position of the SBD signal to the falling edge of the RG signal and recognizes it as the number of data to be transferred. The record and reproduction processing circuit 6 produces the data as the NRZ data to the data flow control circuit 22 on
10 the basis of the recognized number of data to be transferred after the elapse of the reproduction delay time.

According to the embodiment, the magnetic recording and reproducing apparatus is configured on
15 the basis of the control signal (VALID signal) indicating the data output period, so that the control signals are increased but the control circuit can be simplified.

In the recording operation example of the
20 embodiment, the case where the recording delay is increased has been described and accordingly the output timing of the NRZ data is earlier than the assert timing of the WG signal by the recording delay time. However, the recording delay is a conversion delay of
25 the coding circuit 10 or the data recording circuit 11 and since the recording delay is largely different depending on a configuration of the coding circuit, there is a case where the recording delay is small as

described in the prior art. In this case, the output timings of the WG signal and the NRZ data may be coincident as described in the prior art, that is, the VALID signal and the WG signal can be made common.

5 Further, there is a case where a memory for temporarily storing recording data is required in the coding circuit 10 or the record and reproduction processing circuit 6 in order to delay the NRZ data, although it is not shown in the embodiments.

10 ANOTHER EMBODIMENT

 An example of a magnetic recording and reproducing apparatus to which the third embodiment is applied is described. Fig. 19 is a schematic diagram illustrating the magnetic recording and reproducing
15 apparatus including the coding circuit 10 and decoding circuit 16 disposed between the buffer control circuit 23 and the data flow control circuit 22 which can record and reproduce the coded data. In the
embodiment, the data decision circuit 14 and the data
20 correction circuit 15 function as a coding and reproducing circuit.

Recording Operation

 In the recording operation, the coding circuit 10 codes a data string sent from the buffer
25 control circuit 23 and sends it to the data flow control circuit 22 which produces the coded data string

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differently from the above configuration example. The flow control circuit 22 includes, as shown in Fig. 20, the fixed data production circuit 34, the selection circuit 35, the write valid production circuit 60 and an FIFO 38. The FIFO 38 stores data produced from the fixed data production circuit 34 and data produced from the coding circuit 10 in the range indicated by the sequencer 33 and produces the data to the data recording circuit 11 as the NRZ data on the basis of the VALID signal produced by the write valid production circuit 60.

The timing of the VALID signal and the NRZ data is shown in Figs. 21A and 21B. The NRZ data sent from the FIFO 38 is a series of data including PLO, SYNC, DATA, ECC and POST, which are the data string which can be recorded directly through the data recording circuit 11. When the WG signal rises, the NRZ data is directly recorded in the recording medium and accordingly it is easy to control the timing without the need of indicating a record position by means of the above SBD signal.

Reproduction Operation

In the reproduction operation, the data correction signal 15 activates the VALID signal at the same time that the NRZ data is sent out. The VALID signal and the NRZ data are supplied to the FIFO 38 of the data flow control circuit 22 as shown in Fig. 20.

The FIFO 38 takes in the NRZ data when the VALID signal is active and thereafter sends out data to the decoding circuit 16.

5 The detailed timing of the VALID signal is the same as shown in the Fig. 18 except that the NRZ data is data which is not decoded by the decoding circuit 16 and the VALID signal is produced in response to the timing of data outputted to the NRZ data. The rising edge of the SBD signal is produced in response to detection of the SYNC area on the recording medium and the NRZ data and the VALID signal are produced after the elapse of the reproduction delay time starting from the detection of SYNC. The data flow control circuit 22 produces the NRZ data to the buffer control circuit 23 through the decoding circuit 16.

10 According to the embodiment, even in the data recording and reproducing apparatus having the different configuration, the magnetic recording and reproducing apparatus is configured on the basis of the control signal (VALID signal) indicating the data output period, so that the control circuit can be simplified similarly.

ANOTHER EMBODIMENT

25 In the first, second and third embodiment, the magnetic disk apparatus has been described by way of example, while the present invention can be applied to the data recording and reproducing apparatus such as

an optical magnetic disk apparatus and a magnetic tape apparatus other than the above magnetic disk apparatus. Furthermore, the present invention can be also applied to a data reproduction apparatus of LSI level of components constituting the data recording and reproducing apparatus such as the magnetic disk apparatus, the optical magnetic disk apparatus and the magnetic tape apparatus.

According to the data reproduction apparatus of the present invention, since the synchronization information detection signal is not produced from the data reproduction means which produces the output delayed by the reproduction delay time but the synchronization information detection signal is produced from the synchronization information detection means which produces the output without substantial delay, the end position of the block on the recording medium can be calculated exactly on the basis of the synchronization information detection signal without influence of the reproduction delay time. Accordingly, it is not required to provide an additional area (pad area PAD in the magnetic disk) longer than the reproduction delay time in the end of the block in order to ensure that the data reproduction means reads out information of the block from the recording medium. Accordingly, the additional area can be minimized and the effectively usable data storage area can be increased, so that the data recording efficiency can be

improved.

Similarly, reduction of the data recording efficiency due to the recording delay can be reduced to the minimum even in the recording operation.

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CLAIMS:

1. A data reproduction apparatus comprising:
a synchronization information detection circuit for detecting synchronization information of a block to be reproduced from a recording medium in which a series of data string having said synchronization information added thereto is recorded as a block to produce a synchronization information detection signal;
a block end position calculation circuit for calculating an end position of said block on said recording medium on a basis of said synchronization information detection signal; and
a data reproduction circuit for reading out data recorded from said detected synchronization information to said calculated end position of said block from said recording medium to reproduce the data.
2. A data reproduction apparatus according to Claim 1, wherein said data reproduction circuit includes a read/write amplifier, a waveform processing circuit, a data decision circuit, a data correction circuit and a decoding circuit.
3. A data reproduction apparatus according to Claim 1, further comprising a data processing circuit for processing data produced from said data reproduction circuit after elapse of a reproduction delay time on the basis of said synchronization information detection signal.
4. A data reproduction apparatus according to

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Claim 3, further comprising:

a first unit including said synchronization information detection circuit and said data reproduction circuit; and

a second unit including said block end position calculation circuit and said data processing circuit;

wherein said synchronization information detection signal is sent from said first unit to said second unit and said data is sent from said first unit to said second unit after said synchronization information detection signal has been sent.

5. A data reproduction apparatus according to Claim 3, further comprising:

a first unit including said synchronization information detection circuit and said data reproduction circuit; and

a second unit including said block end position calculation circuit and said data processing circuit;

wherein said synchronization information detection signal and said data are sent from said first unit to said second unit and said calculated block end position is notified from said second unit to said first unit.

6. A data reproduction apparatus according to Claim 4, wherein said synchronization information detection signal and said data are sent from said first

unit to said second unit through the same signal line and when synchronization information of a second block continuing to a first block is detected while said data reproduction circuit produces a data string of said first block, outputting of the data string of said first block is temporarily reserved and after said synchronization information detection circuit detects said synchronization information of said second block or after a predetermined time elapses from the time that said synchronization information is not detected, the outputting of the data string of said first block is resumed.

7. A data reproduction apparatus according to Claim 3, further comprising:

a data range prescribing circuit for producing a data settling signal indicative of a range of data produced from said data reproduction circuit;

a first unit including said synchronization information detection circuit, said data reproduction circuit and said data range prescribing circuit; and

a second unit including said block end position calculation circuit and said data processing circuit;

wherein said synchronization information detection signal is sent from said first unit to said second unit and said data and said data settling signal are sent from said first unit to said second unit after said synchronization information detection signal has

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been sent.

8. A data reproduction apparatus comprising:

a format control circuit for activating a reading command signal for commanding to read a block to be reproduced on a recording medium in which a plurality of blocks are recorded as a block unit having a data string including:

bit synchronization information for performing bit synchronization;

symbol synchronization information for performing symbol synchronization;

data;

correction information for correcting said data; and

additional area;

and calculating an end position of said block on said recording medium on the basis of a synchronization information detection signal to inactive said reading command signal;

a synchronization information detection circuit for reading a block on said recording medium during a period that said reading command signal is active and detecting said symbol synchronization information to produce said synchronization information detection signal;

a data reproduction circuit for reproducing said data and said correction information of said block read out from said recording medium during the period

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information added thereto;

a recording circuit for recording said data string in a recording medium as a record data string; and

a control circuit for controlling said data string production circuit and said recording circuit independently;

wherein said control circuit controls said recording circuit and produces said record data string after said data string of said data string production circuit is produced.

11. A data reproduction apparatus according to Claim 10, further comprising:

a first unit including said data string production circuit and said control circuit; and

a second unit including said recording circuit;

wherein said data string and a control signal for controlling said recording circuit by means of said control circuit are sent from said first unit to said second unit and said data string is produced in advance of said control signal.

12. A data reproduction apparatus comprising:

a data production circuit for sending out data;

a coding circuit for coding said data;

a data string production circuit for adding synchronization information to said coded data to

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produce a data string;

a recording circuit for recording said data string as a record data string; and

a format control circuit for controlling said data string production circuit and said recording circuit independently;

wherein said control circuit controls said recording circuit and produces said record data string after when said data string of said data string production circuit is produced.

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ABSTRACT OF THE DISCLOSURE

When the format control circuit detects bit synchronization information in a sector to be reproduced on a magnetic disk, the format control circuit activates a read gate signal for commanding to read out the sector from the magnetic disk. When symbol synchronization information on the magnetic disk is detected, a SYNC detection circuit produces a synchronization information detection signal. The format control circuit calculates an end position of the sector on the magnetic disk on the basis of the synchronization information detection signal to inactivate the read gate signal. The data correction circuit and the decoding circuit reproduce data and ECC in the sector read out from the magnetic disk during the period that the read gate signal is active on the basis of the synchronization information detection signal to produce the data and ECC to a data bus. The data flow control circuit processes the data and ECC on the data bus after the elapse of a reproduction delay time on the basis of the synchronization information detection circuit.

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FIG. 2

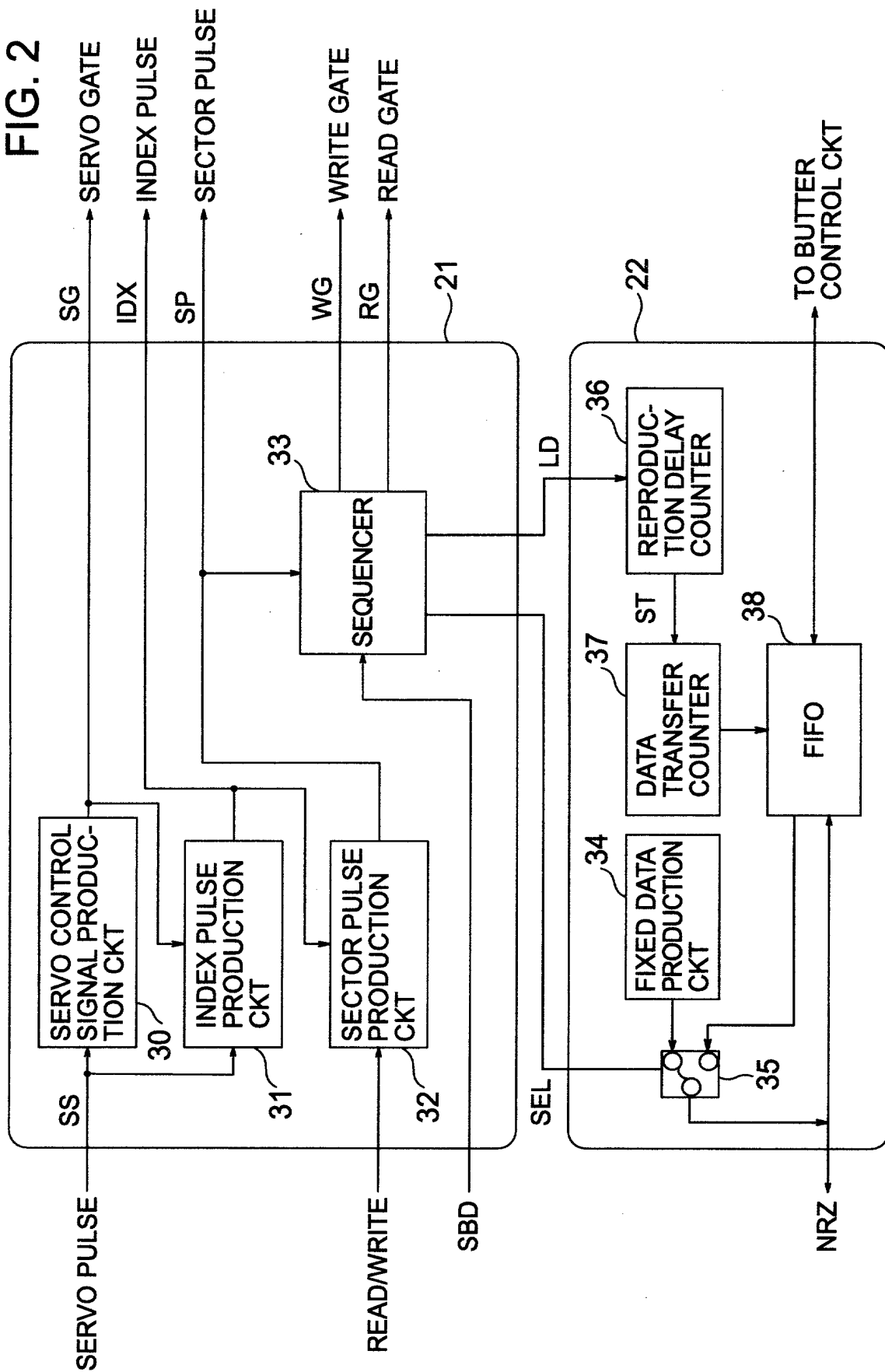


FIG. 3A

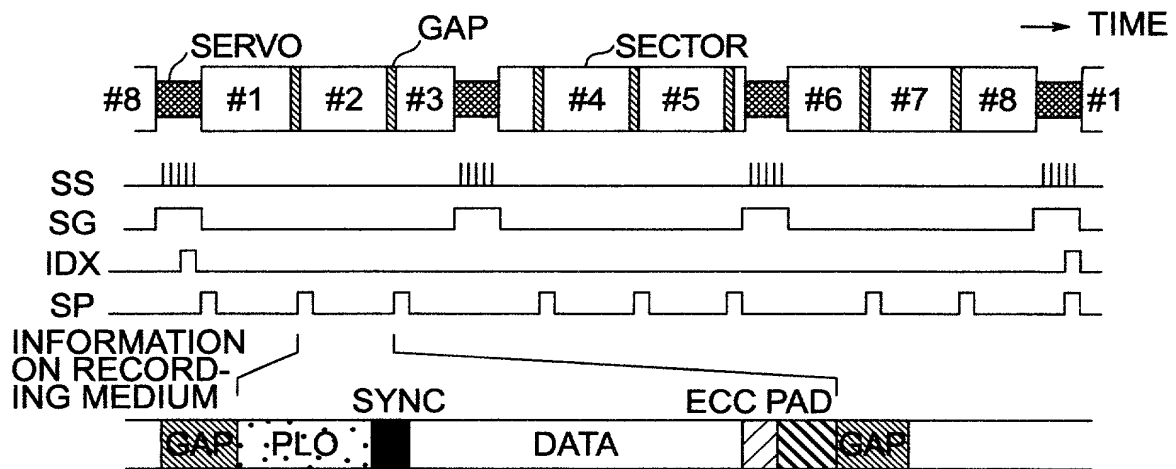


FIG. 3B

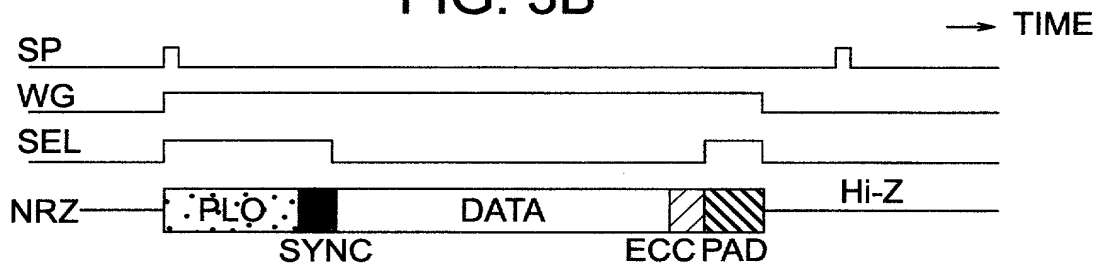


FIG. 3C

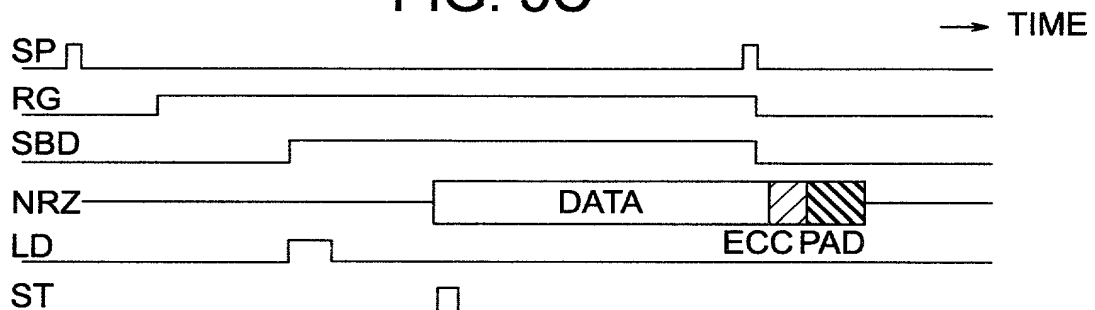


FIG. 4A

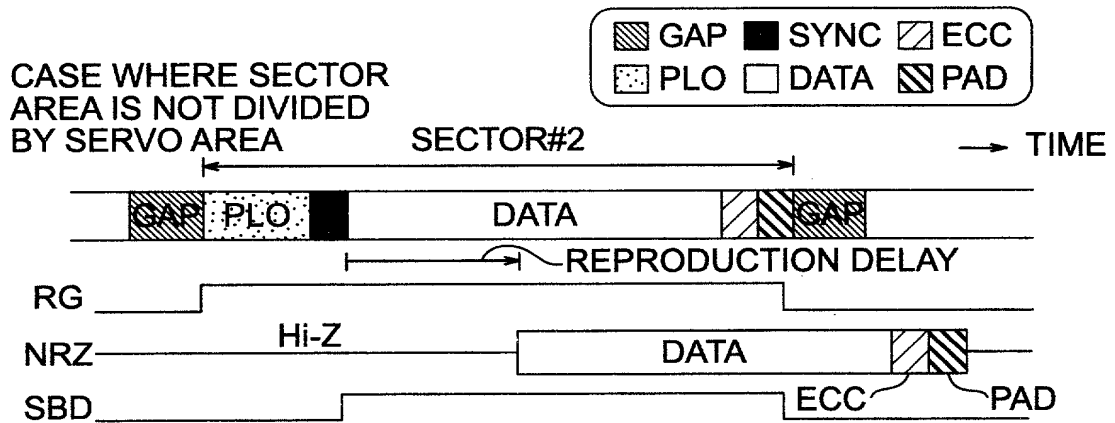


FIG. 4B

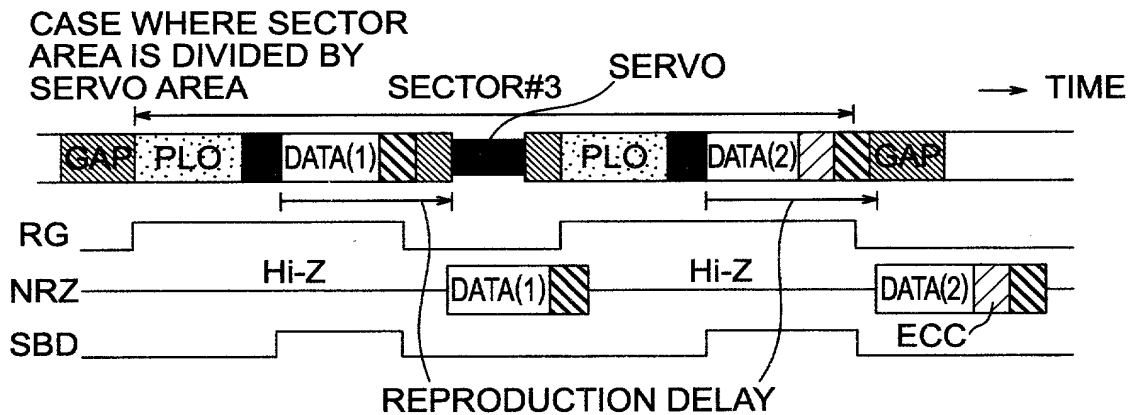


FIG. 5A

CASE WHERE SECTOR AREA IS NOT DIVIDED BY SERVO AREA

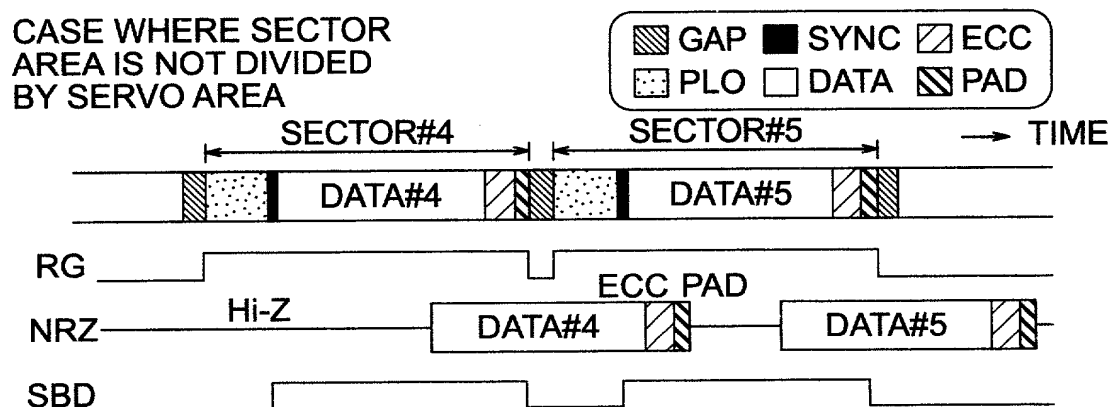


FIG. 5B

CASE WHERE SECTOR AREA IS DIVIDED BY SERVO AREA

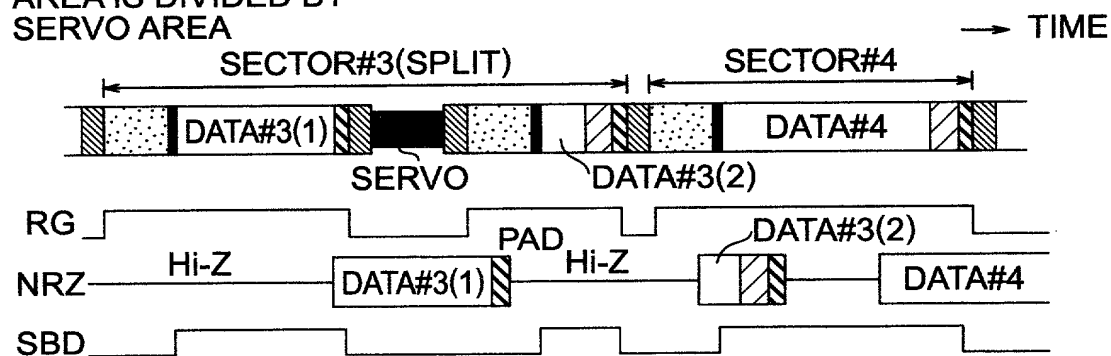


FIG. 6A

CASE WHERE SECTOR AREA IS NOT DIVIDED BY SERVO AREA

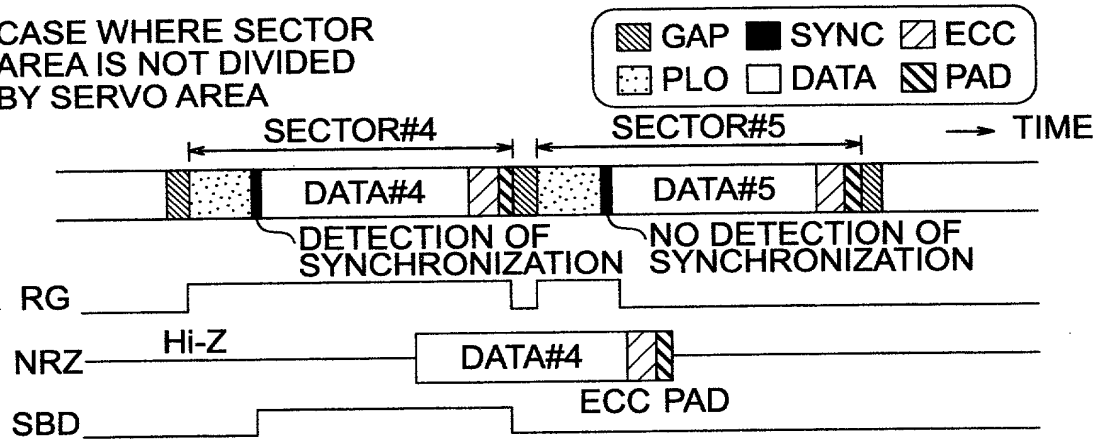


FIG. 6B

CASE WHERE SECTOR AREA IS DIVIDED BY SERVO AREA

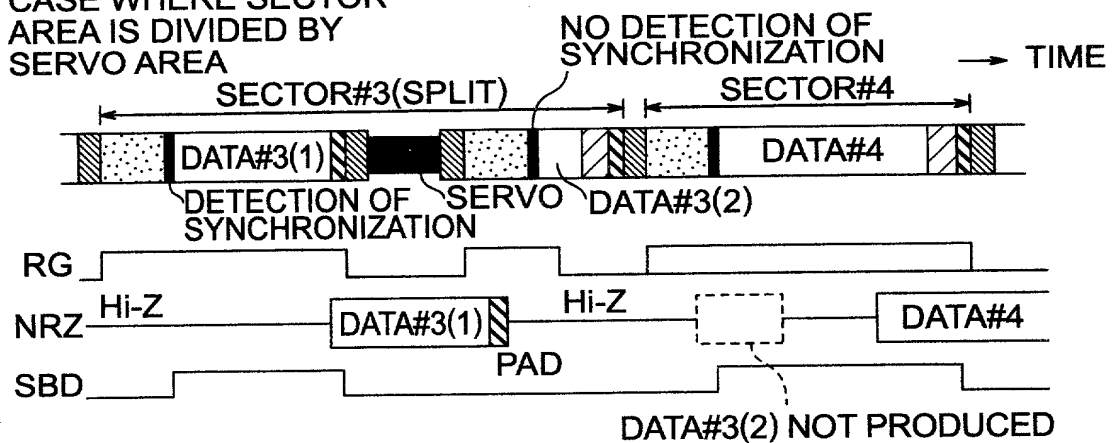


FIG. 7A

USUAL PROCESSING

	PROCESSING BY SEQUENCER 33	PROCESSING BY DATA FLOW CONTROL CKT 22
step1	ACTIVATE "RG" SIGNAL	CONTINUE WHEN DATA IS BEING TRANSFERRED
step2	SYNC DETECTED WITHIN FIXED PERIOD? ("SBD" SIGNAL=ACTIVE)	CONTINUE WHEN DATA IS BEING TRANSFERRED
step3	WAIT DURING PRESCRI- BED NUMBER OF BYTES	WAIT DURING NUMBER OF RE- PRODUCTION DELAY BYTES AND THEN START TO TRANS- FER DATA OF PRESCRIBED NUMBER OF BYTES
step4	INACTIVATE "RG" SIGNAL	CONTINUE WHEN DATA IS BEING TRANSFERRED
step5	WAIT UNTIL SERVO PERIOD PASSES	CONTINUE WHEN DATA IS BEING TRANSFERRED
step6	ACTIVATE "RG" SIGNAL	CONTINUE WHEN DATA IS BEING TRANSFERRED
step7	SYNC DETECTED WITHIN FIXED PERIOD? ("SBD" SIGNAL=ACTIVE)	CONTINUE WHEN DATA IS BEING TRANSFERRED
step8	WAIT DURING PRESCRI- BED NUMBER OF BYTES	WAIT DURING NUMBER OF RE- PRODUCTION DELAY BYTES AND THEN START TO TRANS- FER DATA OF PRESCRIBED NUMBER OF BYTES
step9	INACTIVATE "RG" SIGNAL	CONTINUE WHEN DATA IS BEING TRANSFERRED

FIG. 7B

EXCEPTIONAL PROCESSING(WHEN SYNC BYTE IS NOT DETECTED WITHIN PRESCRIBED TIME)

step1	INACTIVATE "RG" SIGNAL	CONTINUE WHEN DATA IS BEING TRANSFERRED
step2	NOTIFY OCCURRENCE OF DATA ERROR	CONTINUE WHEN DATA IS BEING TRANSFERRED

FIG. 8

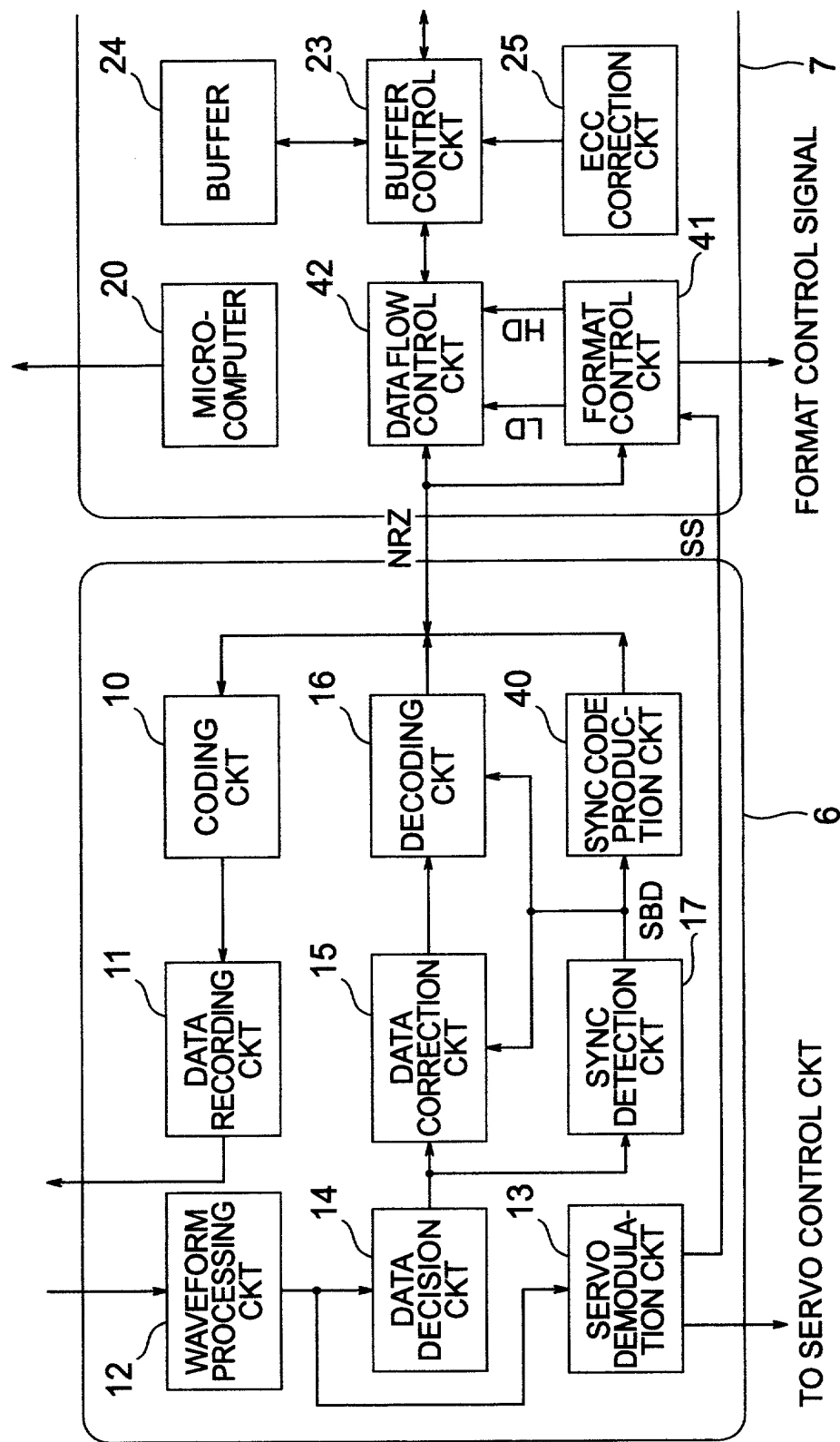
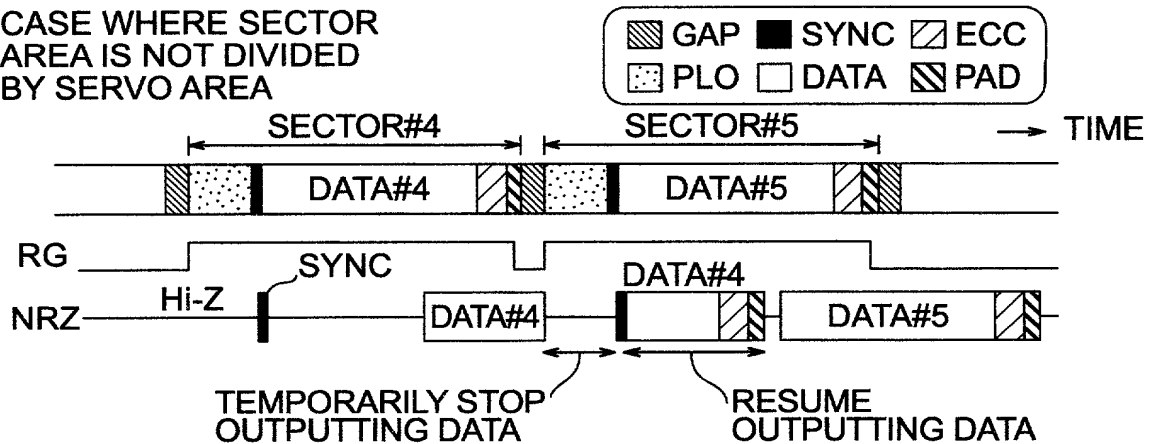


FIG. 9A

CASE WHERE SECTOR AREA IS NOT DIVIDED BY SERVO AREA



CASE WHERE SECTOR AREA IS DIVIDED BY SERVO AREA

FIG. 9B

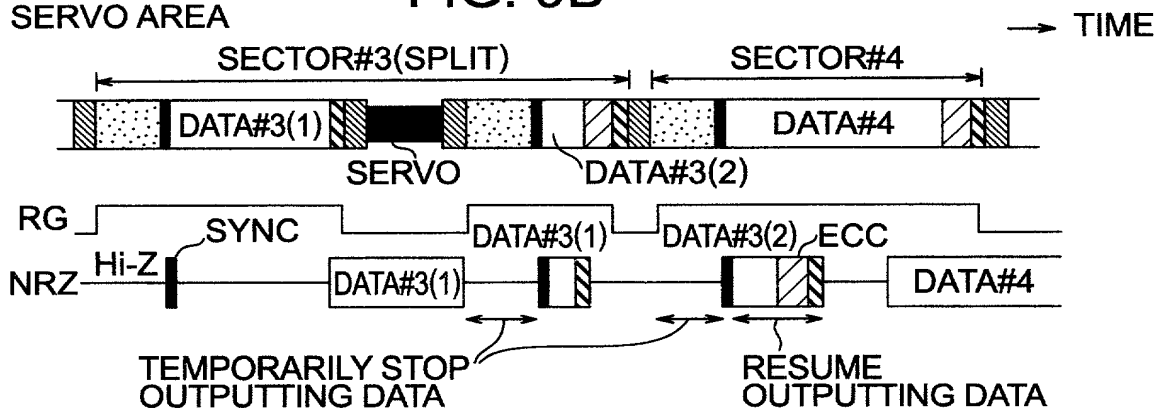


FIG. 10A

CASE WHERE SECTOR AREA IS NOT DIVIDED BY SERVO AREA

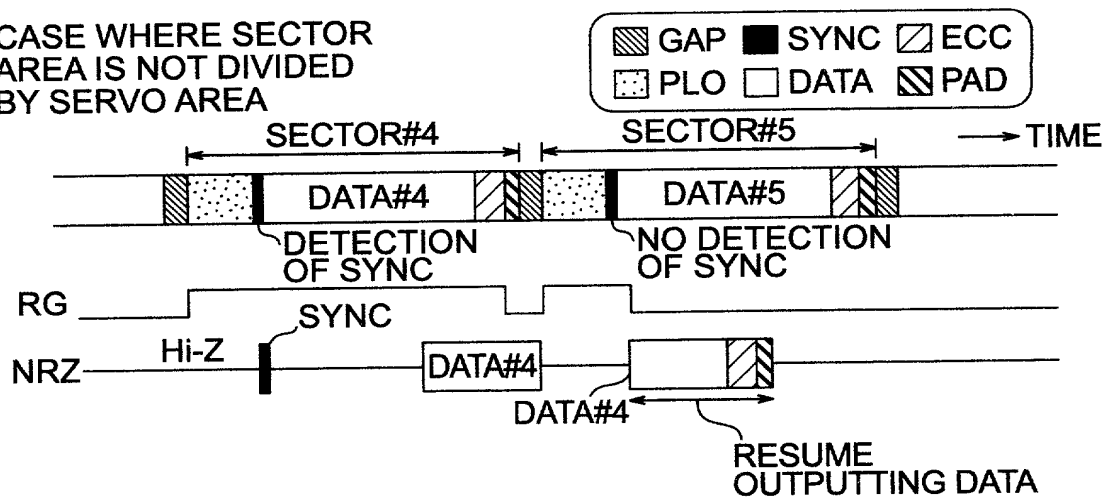


FIG. 10B

CASE WHERE SECTOR AREA IS DIVIDED BY SERVO AREA

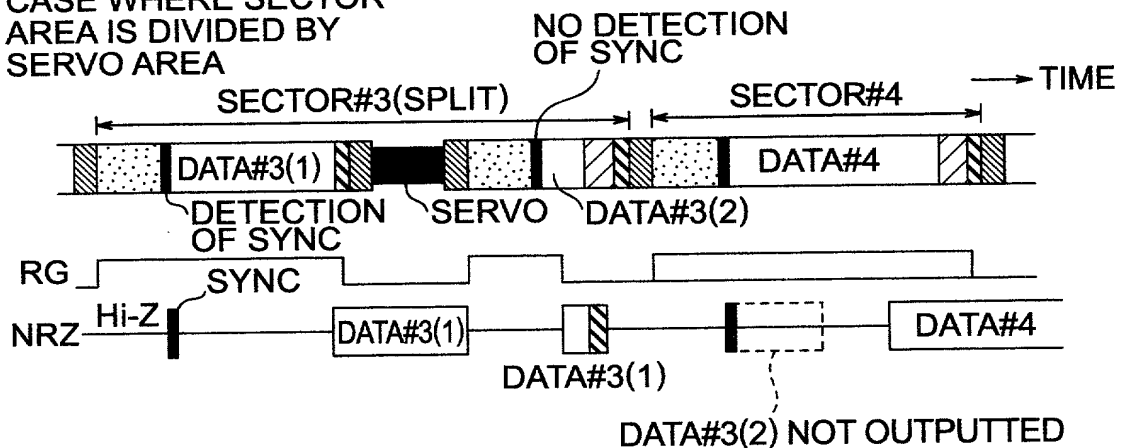


FIG. 11

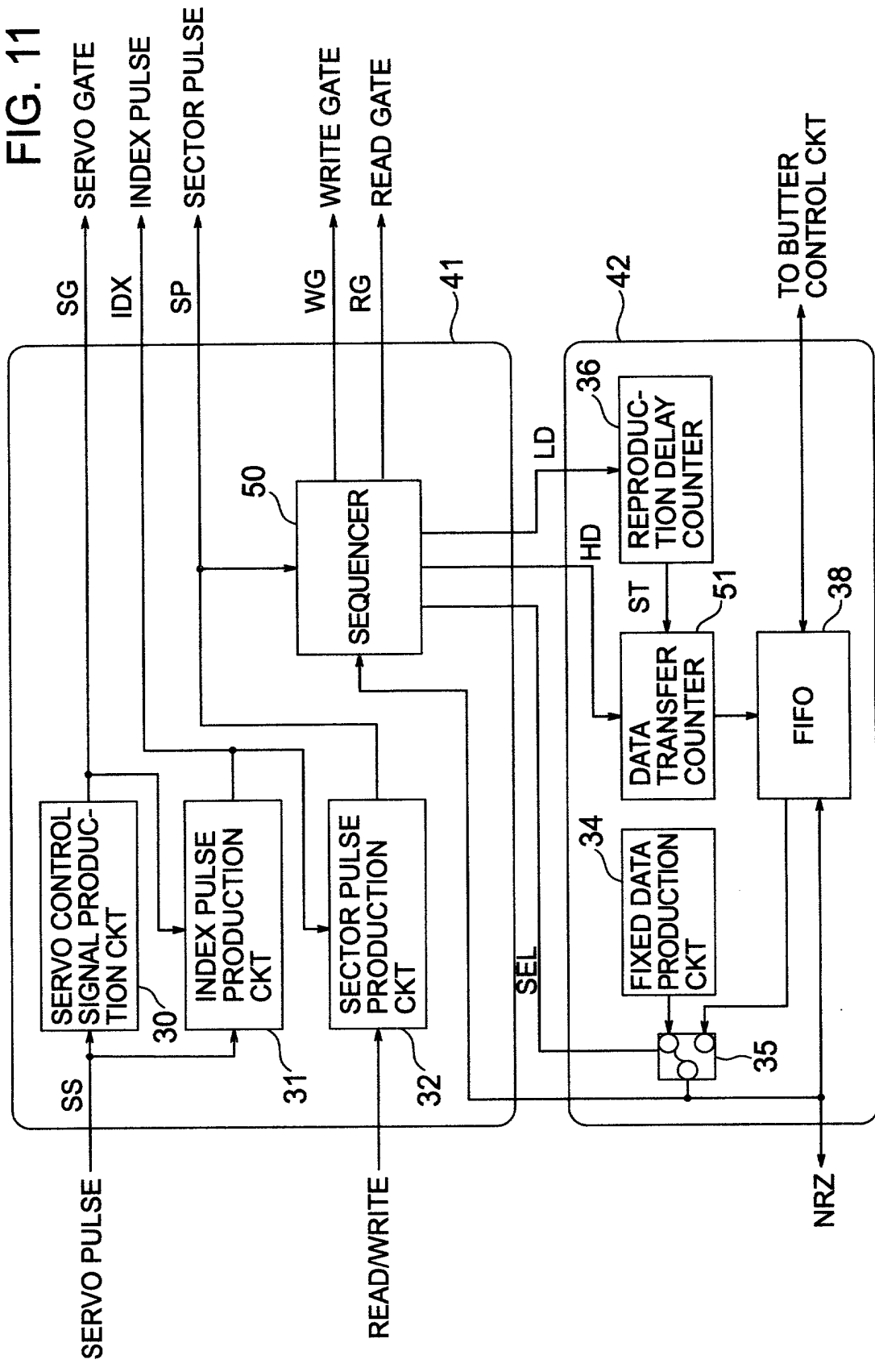


FIG. 12A

USUAL PROCESSING

	PROCESSING BY SEQUENCER 50	PROCESSING BY DATA FLOW CONTROL CKT 42
step1	ACTIVATE "RG" SIGNAL	TEMPORARILY STOP DATA TRANSFER WHEN DATA IS BEING TRANSFERRED
step2	SYNC DETECTED WITHIN FIXED PERIOD? (NRZ DATA=SYNC CODE)	TEMPORARILY STOP DATA TRANSFER
step3	WAIT DURING PRESCRI- BED NUMBER OF BYTES	RESUME DATA TRANSFER WHEN DATA TRANSFER IS TEMPORARILY STOPPED
		WAIT DURING NUMBER OF RE- PRODUCTION DELAY BYTES AND THEN START TO TRANS- FER DATA OF PRESCRIBED NUMBER OF BYTES
step4	INACTIVATE "RG" SIGNAL	DATA TRANSFER CONTINUES
step5	WAIT UNTIL SERVO PERIOD PASSES	DATA TRANSFER CONTINUES
step6	ACTIVATE "RG" SIGNAL	TEMPORARILY STOP DATA TRANSFER WHEN DATA IS BEING TRANSFERRED
step7	SYNC DETECTED WITHIN FIXED PERIOD? (NRZ DATA=SYNC CODE)	TEMPORARILY STOP DATA TRANSFER
step8	WAIT DURING PRESCRI- BED NUMBER OF BYTES	RESUME DATA TRANSFER WHEN DATA TRANSFER IS TEMPORARILY STOPPED
		WAIT DURING NUMBER OF RE- PRODUCTION DELAY BYTES AND THEN START TO TRANS- FER DATA OF PRESCRIBED NUMBER OF BYTES
step9	INACTIVATE "RG" SIGNAL	DATA TRANSFER CONTINUES

FIG. 12B

EXCEPTIONAL PROCESSING(WHEN SYNC CODE IS NOT DETECTED WITHIN PRESCRIBED TIME)

step1	INACTIVATE "RG" SIGNAL	RESUME DATA TRANSFER WHEN DATA TRANSFER IS TEMPORARILY STOPPED
step2	NOTIFY OCCURRENCE OF DATA ERROR WHEN SYNC IS NOT DETECTED IN STEP 7	STOP DATA TRANSFER

FIG. 13

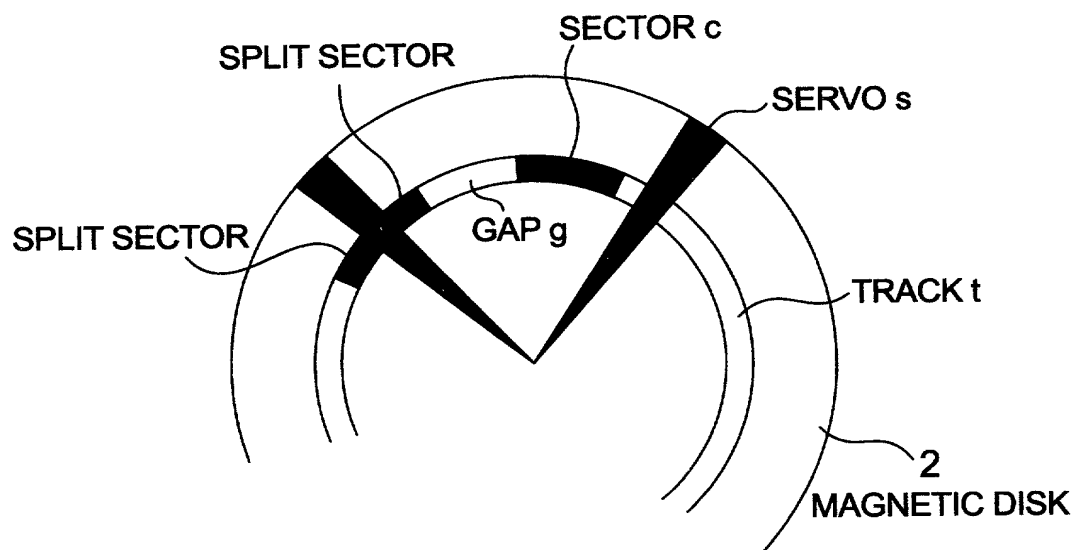


FIG. 14A

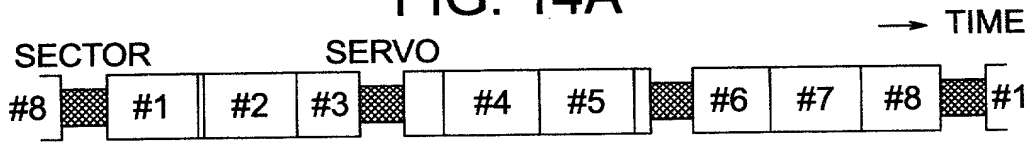


FIG. 14B



FIG. 14C

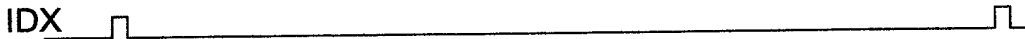


FIG. 14D

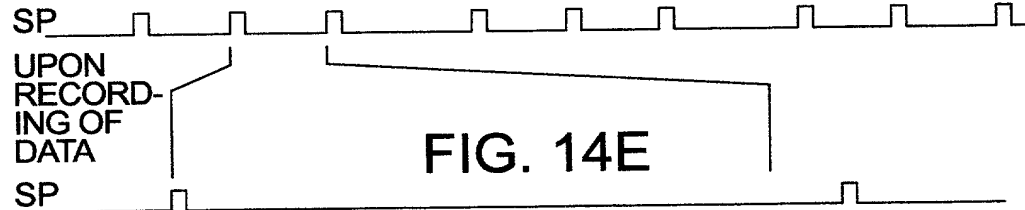
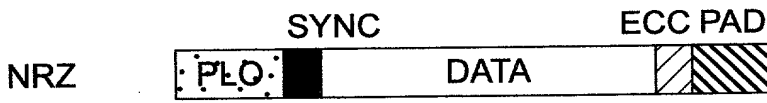


FIG. 14F



FIG. 14G



INFORMATION
ON RECORDING
MEDIUM

FIG. 14H



UPON
REPRODUCTION
OF DATA

FIG. 14I



FIG. 14J



FIG. 14K

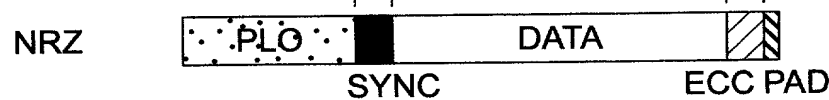


FIG. 16

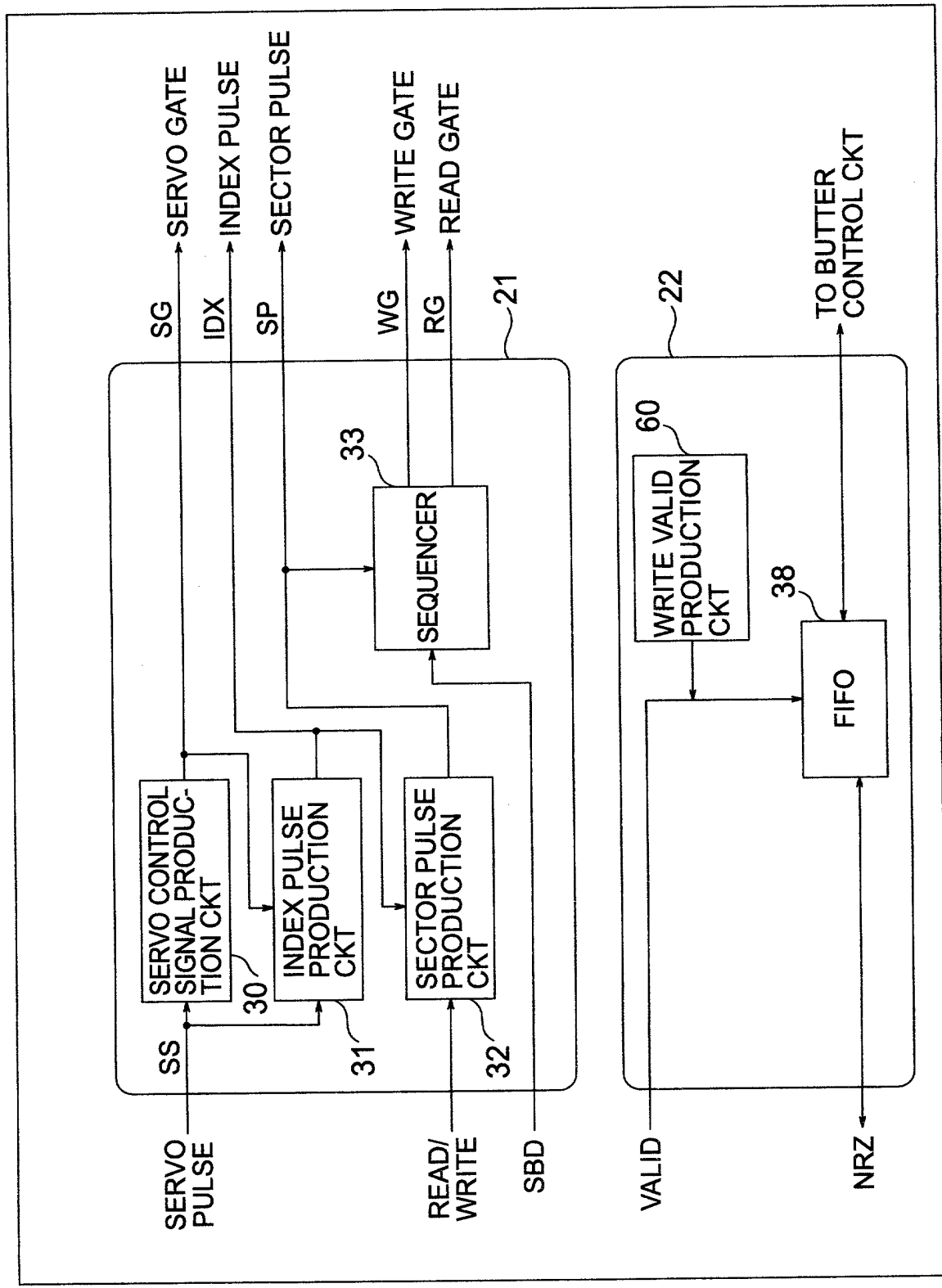


FIG. 17A

CASE WHERE SECTOR
AREA IS NOT DIVIDED
BY SERVO AREA

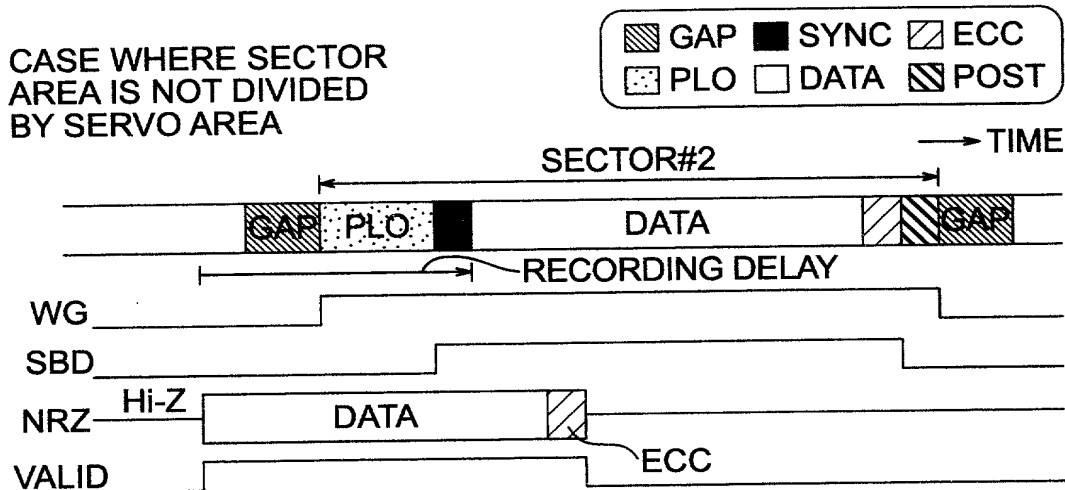


FIG. 17B

CASE WHERE SECTOR
AREA IS DIVIDED BY
SERVO AREA

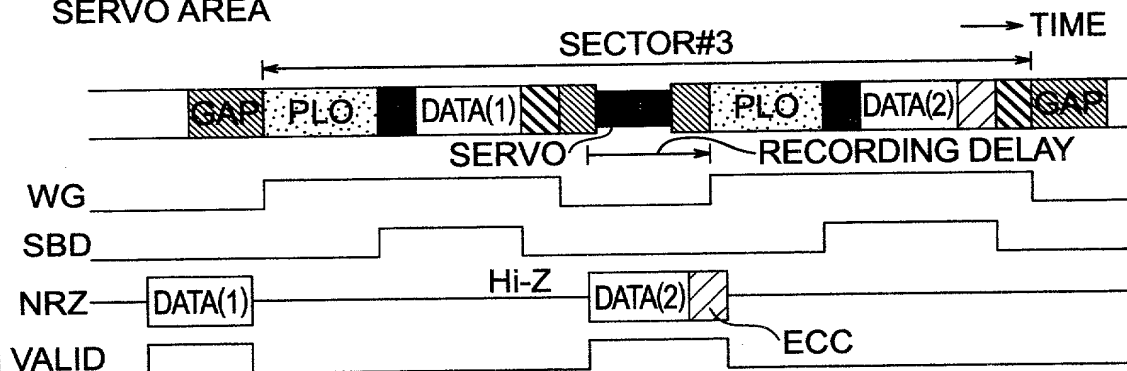


FIG. 18A

CASE WHERE SECTOR AREA IS NOT DIVIDED BY SERVO AREA

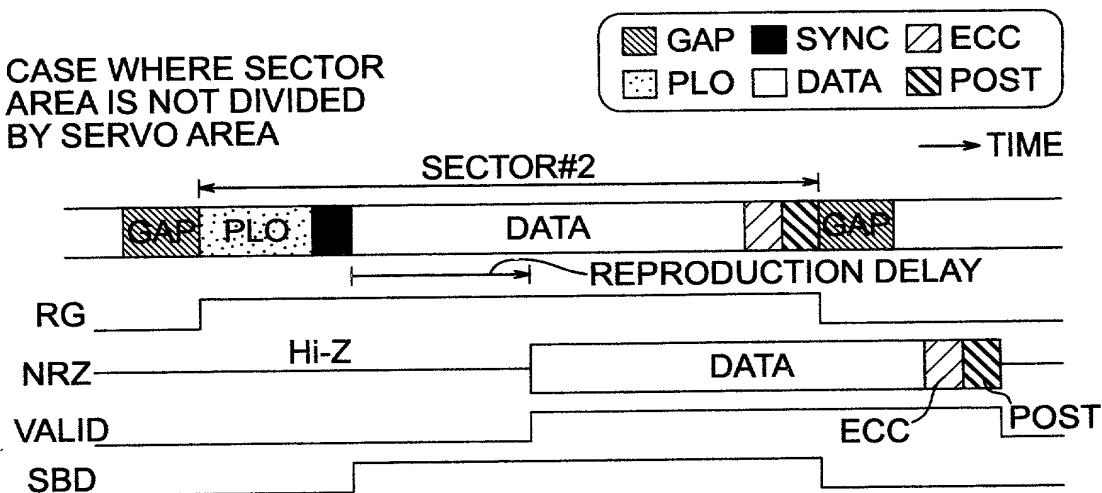


FIG. 18B

CASE WHERE SECTOR AREA IS DIVIDED BY SERVO AREA

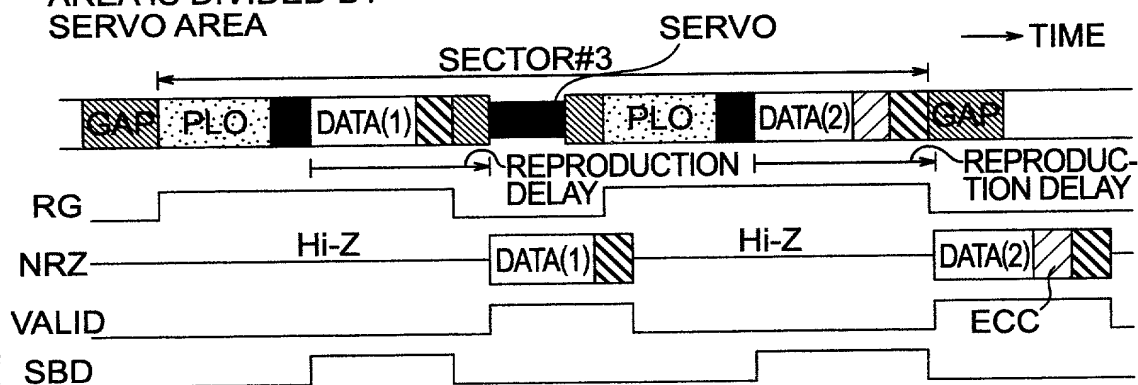


FIG. 19

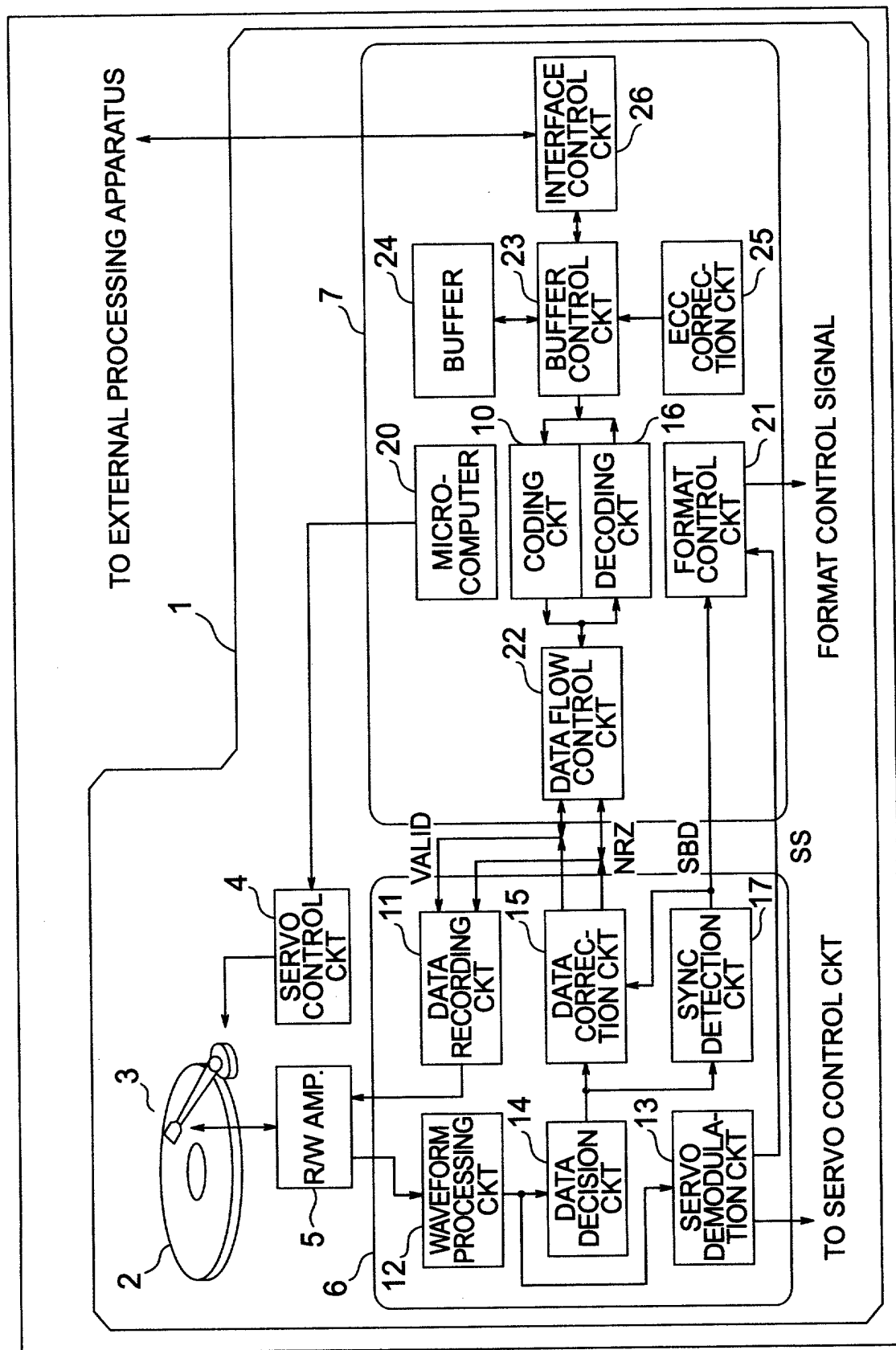


FIG. 20

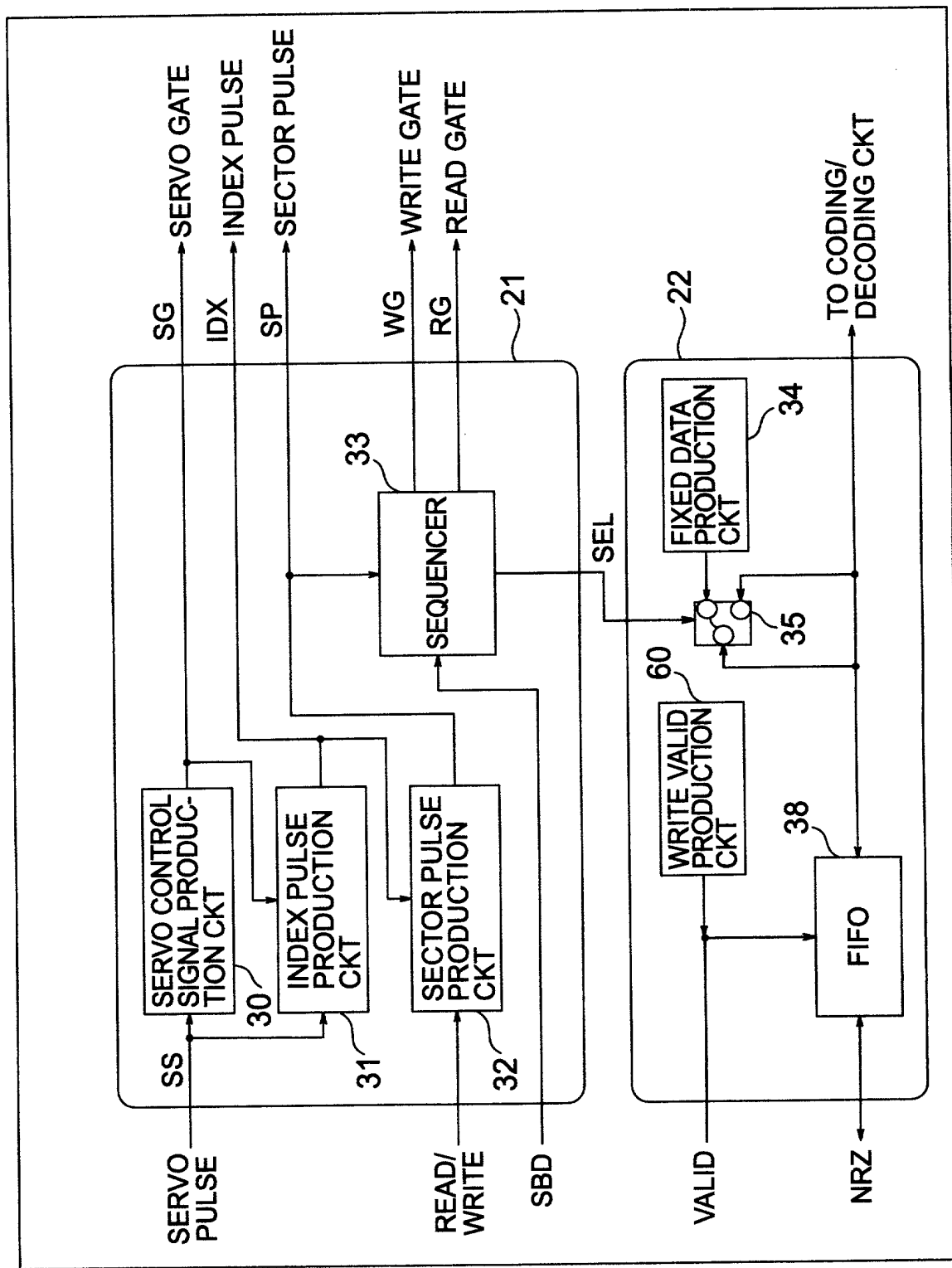


FIG. 21A

CASE WHERE SECTOR AREA IS NOT DIVIDED BY SERVO AREA

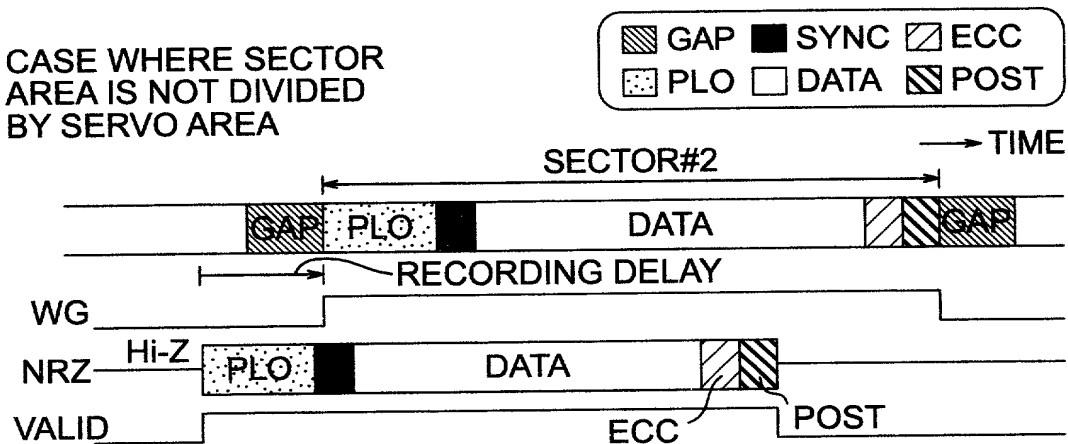
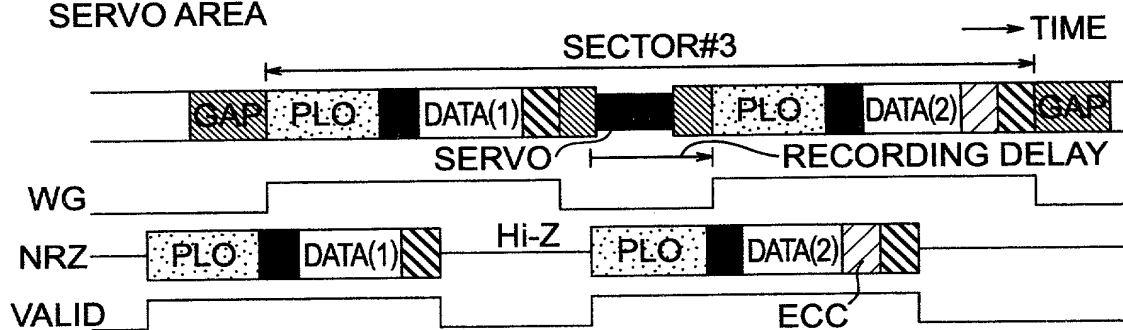


FIG. 21B

CASE WHERE SECTOR AREA IS DIVIDED BY SERVO AREA



08-16-00

A

SOFER & HAROUN, L.L.P.
DECLARATION, POWER OF ATTORNEY & PETITION

ATTORNEY DOCKET NO: 807-005

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE
COMBINED DECLARATION, POWER OF ATTORNEY & PETITION

TYPE OF DECLARATION

- ☒ Utility
☐ Design
☐ Supplemental
☐ Divisional
☐ Continuation
☐ Continuation-in-part
☐ National Stage of the PCT

INVENTORSHIP AND SPECIFICATION IDENTIFICATION

My residence, post office address and citizenship are as stated below next to my name; I believe I am the original, first and sole inventor (if only one is listed below) or a joint inventor (if plural inventors are named below) of the invention entitled:

"DATA REPRODUCTION APPARATUS"

as described and claimed in the specification which

- ☒ is attached hereto.
☐ was filed on _____
☐ as U.S. Serial Number. _____; or
☐ Express Mail No. _____ (as serial number not yet known); and
☐ was amended on _____.
☐ was described and claimed in PCT International Application No. PCT/ / _____
 filed on _____; and
☐ as amended under PCT Article 19 and/or 34 on _____.

REVIEW OF PAPERS AND DUTY OF CANDOR

I have reviewed and understand the contents of the attached specification including the drawing and claims as amended by any amendment referred to below; and
 I acknowledge my duty to disclose information of which I am aware which is material to the examination of this application, in accordance with 37 CFR 1.56(a); and

- ☒ in compliance with this duty there is attached an information disclosure statement.

I hereby claim **foreign priority** benefits under Title 35, United States Code, § 119 of any foreign application(s) for patent or inventor's certificate listed below and have also identified below any foreign applications for patent applications for patent or inventor's certificate having a filing date before that of the application on which priority is claimed:

Prior Foreign Application(s)

			<u>Priority Claimed</u>	
11-271535	Japan	September 27, 1999	<input checked="" type="checkbox"/>	<input type="checkbox"/>
(Number)	(Country)	(Day/Month/Year/Filed)	Yes	No
_____	_____	_____	<input type="checkbox"/>	<input type="checkbox"/>
(Number)	(Country)	(Day/Month/Year/Filed)	Yes	No

I hereby claim the benefit under Title 35, United States Code, § 120 of any **United States Application(s)** listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States Application in the manner provided by the first paragraph of Title 35, United States Code, § 112, I acknowledge the duty to disclose material information as defined in Title 37, Code of Federal Regulations, § 1.56(a) which occurred between the filing date of the prior application and the national or PCT international filing date of this application.

_____	_____	_____
(Application Serial No.)	(Filing Date)	(Status: Patented, Pending, Abandoned)

DECLARATION

I declare that all statements made above of my own knowledge are true and all statements made on information and belief are believed to be true; and these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and such willful false statements may jeopardize the validity of the application or any patent issuing thereon.

POWER OF ATTORNEY

I hereby appoint the following patent attorneys and/or patent agent(s) with full power of appointment, substitution and revocation to prosecute this application, to make alterations and amendments thereto, to receive the patent, and to transact all business in the Patent Office connected therewith.

Joseph Sofer (Reg. No. 34,438)

Robert M. Haroun (Reg. No. 34,345)

Thomas C. Hughes (Reg. No. 42,674)

Please address all telephone calls and correspondence to:

Joseph Sofer
SOFER & HAROUN, L.L.P.
342 Madison Avenue
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New York, New York 10173
Telephone: (212) 697-2800
Facsimile: (212) 697-3004

PETITION

Wherefore, I pray that Letters Patent be granted to me for the invention or discovery described and claimed in the above-mentioned specification and claims, and I hereby subscribe my name to the foregoing Declaration, Power of Attorney & Petition with references to the above-identified specification and claims.

SIGNATURES

Name of first co-inventor: Terumi Takashi
Home Address: Chigasaki-shi, Japan
Post Office Address: Tokyo, Japan
Citizenship: Japan

Inventor's Signature: _____ Date: _____

Name of second co-inventor: Kazuhiko Satake
Home Address: Odawara-shi, Japan
Post Office Address: Tokyo, Japan
Citizenship: Japan

Inventor's Signature: _____ Date: _____